CSM COMPUTER MODEL FOR TBM PERFORMANCE PREDICTION

1. Background

The CSM model for TBM performance prediction was developed by the Earth Mechanics Institute (EMI) over a time period extending over 25 years. The development efforts on the CSM model began with a theoretical analysis of cutter penetration into the rock without any adjacent cuts or free-faces. As shown in Figure 1, this first step was crucial in understanding stress fields and the resultant fractures that are created beneath the penetrating edge of a disc cutter. Initially, the analysis focused on V-profile disc cutters, but later modified to include the constant-cross section discs as they became the industry standard. In this analysis, various previous theories derived from wedge indentation into rock were used as a guide. This analysis helped confirm the occurrence of a highly stressed crushed zone and the radial tension cracks during cutter penetration into the rock.



Figure 1. Stress fields and the resultant fractures beneath the penetrating edge of a disc cutter

The next step was to extend this single cutter analysis into multiple cutter operation to simulate the interaction of adjacent cutting paths on a TBM. This means a free face (cut) exists on one side of the cutter to which the chip formation occurs, as illustrated in Figure 2. In this scenario, the rock under the cutter is again crushed to a fine powder, which behaves in a state of hydrostatic stress, causing radial cracks to form and radiate from this crushed zone or the so-called pressure-bulb. As these cracks are forced to grow, one or more of them reach the neighboring cut, causing rock failure in the form of a chip. Detailed analysis of this chip formation mechanism aided with high-speed movies taken during cutting and chip surface inspections led to the conclusion that rock failure was occurring in tension. As a result, in the first formulation of the CSM model, rock compressive and tensile strengths were used as input to characterize the rock boreability by disc roller cutters. The compressive strength was used to describe the rock crushing beneath the cutter tip while the tensile strength accounted for the chip formation between adjacent cuts. Hence, using these two rock properties, a correlation was developed between cutter thrust force and the depth of penetration achieved as a function of cutter edge geometry and the cutter diameter.



Figure 2. Chip formation between adjacent cuts

Once the equation relating cutter thrust to penetration was established, the cutter rolling force was determined using a ratio called the cutting coefficient. Figure 3 illustrates three cutting forces that are exerted to the tip of the disc cutter during excavation.



Figure 3. Individual forces acting on a cutter

2. Prediction of Penetration Rate in CSM Model

The formulation of the initial model was followed with calibration with actual cutting data obtained from laboratory tests performed on the CSM Linear Cutting Machine (LCM). The LCM allows testing of full size field cutters under field-simulated conditions in terms of cut spacing, penetration, speed, etc (Figure 4). The accuracy of LCM test results has been validated with extensive field TBM data. The statistical analysis of the cutting forces from LCM testing with intact rock properties (such as unconfined compressive strength and tensile strength), cutting geometry (spacing and penetration), and cutter geometry (diameter and tip width) became the basis of the CSM computer model in order to formulate the cutting forces that are exerted on tip of the disc cutter. This made penetration rate prediction possible for a tunnel boring machine in given rock conditions by using the formulation from LCM testing. This also means that one

can make performance prediction without doing any laboratory-cutting test, such as LCM, with an acceptable accuracy.



Y Saddle

Cutter

Cutter

spacing

Figure 4. LCM test set-up and cutting forces recorded

Sled

Load cell

h

Rock

box

Unconfined compressive strength and tensile strength are still the part of CSM database to assess performance prediction of TBMs along with additional special tests, such as Punch Penetration Index test, to characterize the boreability of the intact rock. But, great attention is paid to scrutinizing the rock compressive and tensile strength measurements before they are entered into the CSM model. For compressive strength, all structural failure data are discarded since such data does not represent the true intact strength of the rock. The same holds true for tensile strength measurements. Figure 5 illustrates the failure types that represent types of failures. The failure of a core sample along an existing fracture, joint or bedding/foliation planes during laboratory test is considered as structural failure.



UCS non-structural

UCS structural



BTS non-structural

BTS structural

Figure 5. Failure types for UCS and BTS

Prediction of penetration rate is first based on the new cutters for the entire cutterhead. This value is then adjusted to account for cutter wear as the TBM will always include cutters at different levels of wear during mining. Because of this, a correction factor must be included to account for the weighted average new and worn cutters at a time. The CSM computer model performs this adjustment.



Figure 6. New and worn disc cutters

From the comparison of the model results with field data, it became apparent that the compressive and tensile strengths themselves were not sufficient to fully characterize and describe rock failure by disc cutters. This meant there were some other rock properties, which influenced cuttability in addition to its compressive and tensile strengths. This property was referred to as the toughness, meaning some rocks required either more or less cutting effort than would be predicted based on their strength values alone. In some cases, rock was found to resist efficient chipping with more than usual crushing occurring beneath the cutter tip. In others, rock chipping occurred with less effort than anticipated. Following further theoretical and experimental studies, this toughness issue was addressed by two methods. First was the adoption of the Punch Penetration test as one measure of rock toughness. The punch test was originally developed by Ingersoll-Rand for estimating raise borer performance and later adapted and used by Robbins for TBM performance prediction. This test is described in literature; it basically involves the penetration of a cone-shaped indentor into the rock and analyzing the load vs. penetration curve recorded during the test (Figures 7). This slope is then used to provide a measure of rock toughness. Another method to assist in defining rock toughness is the thinsection petrographic analysis. It was found that in some rocks, certain grain/matrix characteristics contributed to rock exhibiting certain toughness by impeding efficient chipping. In such rock types, extensive crushing of rock was seen to occur in the cutter path prior to formation of chips. Petrographic evaluations of such rocks revealed the occurrence of grain suturing/interlocking, which made the rock fabric more difficult to "tear apart", hence the increased difficulty of chipping during TBM operation. As a result of these findings, the Punch Penetration index and the observations from thin-section analysis (Figure 8) were also added as input parameters to the CSM model. Also considered were rock porosity and grain size. Especially rock porosity effects the fracturing since the chipping mechanics in disc cutting is based on the fracture propagation between adjacent cuts as described in Figure 2. All these factors are incorporated into the model through empirical correlations with field data from various job sites.



Figure 7. Punch Penetration Index Test (A) Test Set up (B) Penetration-Force Plot



Figure 8. Example analysis of Thin-sections

Further, the tensile strength (Brazilian) tests are evaluated from a viewpoint of sample orientation with respect any bedding/foliation, which might be present. As shown in Figure 9, in

rocks exhibiting directional behavior due to existence of bedding/foliation, the Brazilian disks need to be oriented so that failure occurs in more or less the same direction as chipping between cutter paths.



perpendicular to foliation

The CSM model predicts the penetration rate without any consideration given to the influence of existing joints/fissures in the rock. To account for these effects, the model makes use of the correlation factors developed for joint effects by the Norwegian Geotechnical Institute (NTNU). Depending on joint/fissure spacing and angle that these weakness planes make with the tunnel axis (i.e. the alpha angle), NTNU has derived a set of relationships between TBM penetration rate and the fracturing factor. The CSM model results are then adjusted accordingly to account for the joint/fissure effects using the relationships similar to those developed by NTNU.

3. Model Description

The equations and the specific algorithms used in the CSM model for relating cutter force to penetration are proprietary and are not disclosed to third parties. However to demonstrate how the model functions, following is a step-by-step explanation as to the logic, which the model utilizes to estimate the TBM penetration rate and cutter life. Figure 10 is a flow chart, which shows the general steps involved in making performance estimates. Once the appropriate rock and geologic data is entered into the model, one of two options can be exercised. If the predictions are to be developed for an existing machine, the model then asks for relevant information about the machine, including cutter type, layout, type of machine, all machine specifications in terms of thrust, torque, power, rpm, etc. If it is desired to use a new machine, the model will then develop the required specifications and provide a cutterhead layout determined to be optimal for the rock and geologic conditions anticipated. This also covers the selection of the best cutter geometry.



Figure 10. Logic of the CSM Model for TBM performance prediction

Figure 11 shows the model window where the machine specifications are entered together with power and thrust efficiency factors. The model then asks whether the actual cutterhead is layout is available and if so, whether the estimates are to be developed using actual layout or the average cutter spacing. These two approaches give very close results. The only difference is that by using the actual head layout, the model can also calculate individual loads, which vary as transition begins to occur from face to gage cutters (Figure 12).

roject and Tunnel Infor	mation	Machine Information —	
Project Name:	Golden Tunnel	Machine Type:	Open Beam
Project Location:	Golden	Machine Model:	Model XYZ
Contractor:	CSM	Cutterhead Diameter:	23.18 ft
Owner:	EMI	Number of Cutters:	50
Tunnel Length:	25000 ft	Cutterhead RPM:	8.3
Tunnel Diameter:	23.18 ft	Total Installed Thrust	2500000 lbs.
uttler Information ——		Thrust Efficiency:	0.9 3850 hp
Cutter Diameter:	19 💌 in	Drive Efficiency:	0.9
Cutter Tip Width:	0.75 • in		
Max. Cutter Load:	70000 • Iks		
Max. Linear Speed:	500 <u>*</u> ft/min	OK Oper	Cancel
	400		in the second second

Figure 11. Data Input Window for CSM Model



Figure 12. Cutterhead layout

The next step is to perform the calculations using the force-penetration algorithms built into the model. The model accomplishes the required calculations using an iterative approach. It starts from a low ROP and gradually increases it until one or more cutter or machine limits are reached (Figure 13). It then records the corresponding penetration rate as the maximum achievable ROP for the rock and geologic conditions anticipated. It follows the same procedure for all other rock types to be encountered in the tunnel. All estimates are then summarized and listed in a tabular form. As noted previously, the basic penetration is then adjusted by the model to account for joints/foliation, porosity and rock toughness.

Machine Thrust :	O.K.	100%	of machine thru
Machine Torque :	O.K.	63%	of machine torq
Machine Power :	O.K.	63%	of machine pow
Cutter Load Capacity:	0.K.	71%	of max. cutter lo
ROP Limit:	O.K.	37%	of ROP Limit use
		Return to	Main Menu
Basic Penetration : 0.23	in/rev	Return to	Main Menu
Basic Penetration : 0.23 ROP : 9.3	in/rev ft/hr	Return to	Main Menu
Basic Penetration : 0.23 ROP : 9.3 Naximum ROP controlled by <u>Machine Th</u>	in/rev ft/hr h <u>rust</u>	Return to	Main Menu

Figure 13. Calculation of ROP

The model can also produce a plot of cutter load distributions over the cutterhead. An example of this is shown in Figure 14.



Figure 14. Thrust, Power and ROP at different rock strengths

The CSM model also develops an estimate of cutter life and the resultant cutter costs using the Cerchar abrasivity index. This test, which was originally developed by the French Coal Mine Research Institute, has been found to provide an accurate measure of rock abrasivity for disc cutter usage. The test essentially involves scratching the fresh rock surface with a steel pin made of the same material as the cutter itself (Figure 15). The tip loss resulting from a series of surface scratches is then converted b a cutter life index using field-lab data correlations. Using the Cerchar abrasivity index and the calculated ROP, the model then makes an estimate of cutter life in terms of hours of operation and/or the cubic yards of excavation before cutter replacement becomes necessary. If cutter hub assembly and the ring/spares costs are available, cutter costs are determined as dollars per cubic yards of excavation.



Figure 15. Cerchar Abrasivity Test Set-up

4. Conclusion

The CSM performance prediction model is subjected to continual improvements as more field data is acquired and additional calibrations are performed. This is an ongoing process, which serves to steadily enhance the accuracy of the model. The CSM model results also, in general, agree with the two other most widely used TBM performance prediction models, namely the NTNU model and the Robbins model.

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