You can try both problems below, but you will only receive credit for the most correct solution.

1. (10pts) In a 1+2D spacetime (based on SO(1,2) invariance) you have a vector with components $V^{\mu} = \begin{pmatrix} 1 \\ 1 \\ 1 \end{pmatrix}$ and a (1,1)-tensor with components $M^{\rho}_{\ \mu} = \begin{pmatrix} 1 & 1 & 1 \\ 1 & 1 & 1 \\ -1 & -1 & -1 \end{pmatrix}$ when evaluated in a certain reference frame. Find the components of $M^{\rho\prime}_{\ \mu}, V^{\mu\prime}$ after a transformation described by $\Lambda^{\nu\prime}_{\ \nu} = \begin{pmatrix} \gamma & 0 & \beta\gamma \\ -\beta\gamma & 0 & -\gamma \\ 0 & 1 & 0 \end{pmatrix}$.

First of all
$$M^{A}N^{M} = \begin{pmatrix} 1 & 1 & 1 \\ 1 & 1 & 1 \\ 1 & 1 & 1 \end{pmatrix} \begin{pmatrix} 1 & 3 \\ 1 & 3 \\ -3 \end{pmatrix} \equiv A^{M}$$

and it transforms like a vector, i.e. $A^n \rightarrow A^n' = \Lambda^{n'} \wedge A^n$ hence $A^{n'} = \begin{pmatrix} 8 & 0 & 88 \\ -88 & 0 & -8 \end{pmatrix} \begin{pmatrix} 3 \\ -3 \end{pmatrix} = \begin{pmatrix} 38 - 388 \\ -388 + 38 \end{pmatrix}$

2. (10pts) Using the 2D rotation matrix $\Lambda^{i}{}_{i} = \begin{pmatrix} \cos\theta & \sin\theta \\ -\sin\theta & \cos\theta \end{pmatrix}$ as it acts on a displacement vector $dx^{i} = \begin{pmatrix} dx \\ dy \end{pmatrix}$, show explicitly that the combination $dx^{i}dx_{i}$ is invariant, i.e. $dx^{i}dx_{i} = dx^{i'}dx_{i}$, by transforming dx^{i} and dx_{i} separately, and then combining the results to show that what you get is the same as what you started with.

$$dx' \rightarrow dx'' = \Lambda'' : dx' = \begin{pmatrix} \cos \theta & \sin \theta \\ -\sin \theta & \cos \theta \end{pmatrix} \begin{pmatrix} dx \\ dy \end{pmatrix} = \begin{pmatrix} \cos \theta dx + \sin \theta dy \\ -\sin \theta dx + \cos \theta dy \end{pmatrix}$$

$$dx' \rightarrow dx'' = \Lambda'' : dx' = dx' : \Lambda'' : r = (dx dy) \begin{pmatrix} \cos \theta & -\sin \theta \\ \sin \theta & \cos \theta \end{pmatrix}$$

$$5: n\theta = \cos \theta$$

= (dxc050+d75:10, -dx5:19+d,ca0)

$$dx^{i}dx; \rightarrow dx^{i}dx_{i} = dx_{i}dx^{i}$$

$$= (dx_{i}oso + dy_{i}s_{i}no_{i} - dx_{i}s_{i}no_{i} + s_{i}no_{i}dy_{i} + s_{i}no_{i}dy_{i}dy_{i} + s_{i}no_{i}dy_{i}dy_{i} + s_{i}no_{i}dy_{i}dy_{i} + s_{i}no_{i}dy_{i}dy_{i}$$

$$= (cos_{i}o + s_{i}n_{i}o)dx_{i} + (s_{i}n_{i}o + cos_{i}o)dy_{i}$$

$$= dx_{i} + dy_{i}$$