

A Finite Difference Method for Modeling Seismic Wave Propagation

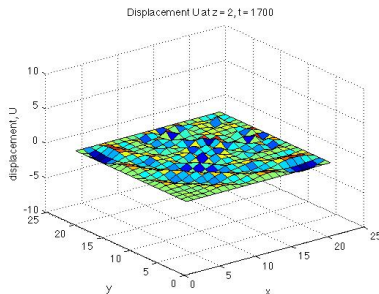
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Capstone Final Project

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Why model seismic waves?

- Information about the material properties and structure of the earth
- Loss estimation
- Future earthquake scenarios



- FDMs were first use in the 1960's
- Equation of Motion:

$$\rho \ddot{u}_i - \sigma_{ij,j} - f_i = 0$$

ρ : material density, \ddot{u}_i : particle acceleration, $\sigma_{ij,j}$: stress tensor, f : forcing function

- Constitutive Relation: relationship between the stress and the strain of a medium

$$\sigma_{ij} = \kappa \epsilon_{kk} \delta_{ij} + 2\mu \left(\epsilon_{ij} - \frac{1}{3} \epsilon_{kk} \delta_{ij} \right)$$

κ, μ, λ : bulk, shear, and elastic moduli, ($\lambda = \kappa - \frac{2}{3}\mu$), σ : stress, ϵ : strain

■ Displacement:

$$\rho \ddot{u}_i = [(\kappa - \frac{2}{3}\mu)u_{k,k}]_{,i} + (\mu u_{i,j})_{,j} + (\mu u_{j,i})_{,j} + f_i$$

- Let u, v, w be the x, y, z components of the displacement. For $\phi \in \{u, v, w\}$, let $\Phi \in \{U, V, W\}$ be the corresponding approximation

$$\phi(x_i, y_j, z_k, t_m) \approx \Phi_{i,j,k}^m$$

with uniform spatial step h and time step Δt ,

$$x_i = ih, y_j = jh, z_k = kh, t_m = m\Delta t$$

■ Central difference approximations

$$\frac{d^2\phi}{dx^2} = \frac{\phi(x-h) - 2\phi(x) + \phi(x+h)}{h^2}, \quad \frac{d\phi}{dx} = \frac{\phi(x+h) - \phi(x-h)}{2h}$$

■ Must account for mixed and non-mixed derivatives

Define auxiliary function $\phi = \mu u_{,x}$. Then

$$\phi_{,x}|_{i,j,k} = \frac{\phi_{i+1/2,j,k} + \phi_{i-1/2,j,k}}{h}$$

$$\phi_{,z}|_{i,j,k} = \frac{\phi_{i,j,k+1/2} - \phi_{i,j,k-1/2}}{h}$$

We need to approximate $\phi_{i+1/2,j,k}$, $\phi_{i-1/2,j,k}$, $\phi_{i,j,k+1/2}$ and $\phi_{i,j,k-1/2}$

■ Non-mixed:

$$\phi_{,x}|_{i,j,k} = \frac{\phi_{i+1/2,j,k} + \phi_{i-1/2,j,k}}{h}$$

$$\phi_{i+1/2,j,k} = \frac{1}{h} \mu_{i+1/2,j,k}^x (U_{i+1,j,k} - U_{i,j,k})$$

$$\phi_{i-1/2,j,k} = \frac{1}{h} \mu_{i-1/2,j,k}^x (U_{i,j,k} - U_{i-1,j,k})$$

■ Mixed:

$$\phi_{,z}|_{i,j,k} = \frac{\phi_{i,j,k+1/2} - \phi_{i,j,k-1/2}}{h}$$

$$\phi_{i,j,k+1/2} = \frac{1}{4h} \mu_{i,j,k+1/2} (U_{i+1,j,k+1} - U_{i-1,j,k+1} + U_{i+1,j,k-1} - U_{i-1,j,k-1})$$

$$\begin{aligned}
U_{i,j,k}^{m+1} = & \frac{1}{h^2} [\lambda_{i+1,j,k}^x (U_{i+1,j,k}^m - U_{i,j,k}^m) - \lambda_{i-1,j,k}^x (U_{i,j,k}^m - U_{i-1,j,k}^m) \\
& + 2(\mu_{i+1,j,k}^x (U_{i+1,j,k}^m - U_{i,j,k}^m) - \mu_{i-1,j,k}^x (U_{i,j,k}^m - U_{i-1,j,k}^m)) \\
& + \mu_{i,j+1,k}^y (U_{i,j+1,k}^m - U_{i,j,k}^m) - \mu_{i,j-1,k}^y (U_{i,j,k}^m - U_{i,j-1,k}^m) \\
& + \mu_{i,j,k+1}^z (U_{i,j,k+1}^m - U_{i,j,k}^m) - \mu_{i,j,k-1}^z (U_{i,j,k}^m - U_{i,j,k-1}^m) \\
& + \frac{1}{4} [\lambda_{i,j+1,k}^y (V_{i,j+1,k}^m + V_{i+1,j+1,k}^m - V_{i,j-1,k}^m - V_{i+1,j-1,k}^m) \\
& - \lambda_{i,j-1,k}^y (V_{i-1,j+1,k}^m + V_{i,j+1,k}^m - V_{i-1,j-1,k}^m - V_{i,j-1,k}^m) \\
& + \lambda_{i,j,k+1}^z (W_{i,j,k+1}^m + W_{i+1,j,k+1}^m - W_{i,j,k-1}^m - W_{i+1,j,k-1}^m) \\
& - \lambda_{i,j,k-1}^z (W_{i-1,j,k+1}^m + W_{i,j,k+1}^m - W_{i-1,j,k-1}^m - W_{i,j,k-1}^m) \\
& + \mu_{i+1,j,k}^y (V_{i+1,j,k}^m + V_{i+1,j+1,k}^m - V_{i-1,j,k}^m - V_{i-1,j-1,k}^m) \\
& - \mu_{i-1,j,k}^y (V_{i+1,j-1,k}^m + V_{i+1,j,k}^m - V_{i+1,j-1,k}^m - V_{i-1,j,k}^m) \\
& + \mu_{i+1,j,k}^z (W_{i+1,j,k}^m + W_{i+1,j,k+1}^m - W_{i-1,j,k}^m - W_{i-1,j,k-1}^m) \\
& - \mu_{i-1,j,k}^z (W_{i-1,j,k+1}^m + W_{i,j,k+1}^m - W_{i-1,j,k-1}^m - W_{i,j,k-1}^m)] + F_{i,j,k}^{x,m}
\end{aligned}$$

$$L_{\gamma,\gamma}(\mathbf{a}, \phi) = \frac{1}{h^2} [\mathbf{a}^{\gamma+} (\phi_+^m - \phi^m) - \mathbf{a}^{\gamma-} (\phi^m - \phi_-^m)], \mathbf{a}^{\gamma+} = \frac{1}{h} \left[\int_{\gamma_n}^{\gamma_{n+1}} \frac{1}{\mathbf{a}} d\gamma \right]^{-1}$$

$$\gamma \in \{x, y, z\}, \mathbf{a} \in \{\mu, \lambda\} \phi \in \{U, V, W\}$$

$$L_{\gamma,\eta}(\mathbf{a}, \phi) = \frac{1}{4h^2} [\mathbf{a}^{\eta+} (\phi_{2+}^m + \phi_{3+}^m - \phi_{2-}^m - \phi_{3-}^m) - \mathbf{a}^{\eta-} (\phi_{1+}^m + \phi_{2+}^m - \phi_{1-}^m - \phi_{2-}^m)]$$

$$U_{i,j,k}^{m+1} = 2U_{i,j,k}^m - U_{i,j,k}^{m-1} + \frac{\Delta t^2}{\rho_{i,j,k}} [$$

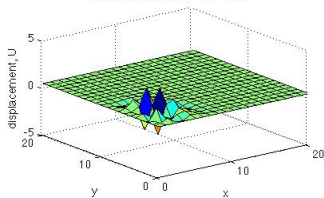
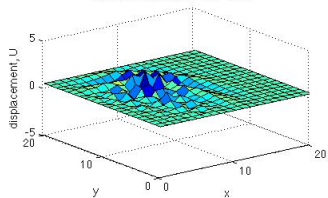
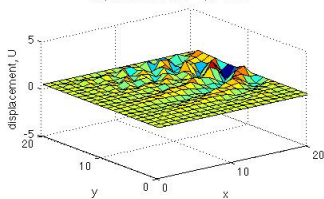
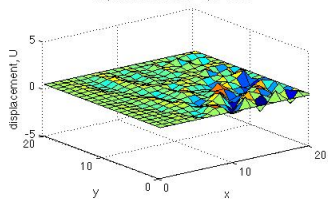
$$L_{xx}(\lambda, U) + 2L_{xx}(\mu, U) + L_{yy}(\mu, U) + L_{zz}(\mu, U)$$

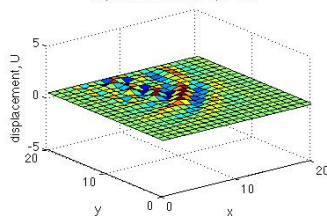
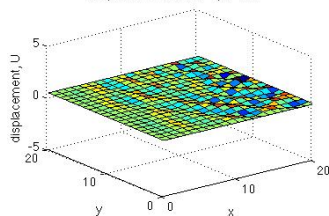
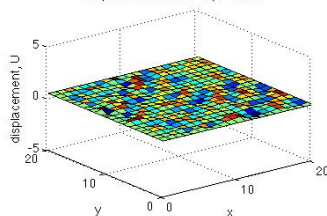
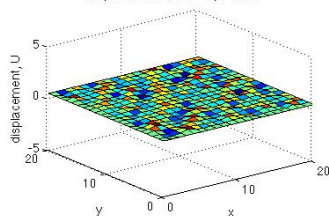
$$L_{yx}(\lambda, V) + L_{zx}(\lambda, W) + L_{xy}(\mu, V) + L_{xz}(\mu, W)] + F_{i,j,k}^{x,m}$$

Stability condition for a second order central difference formula on the general equation of motion in an isotropic, homogeneous medium:

$$\Delta t^2 \leq \frac{h^2}{2\alpha^2(1 + 2\beta^2/\alpha^2)}$$

where $\alpha = \sqrt{\frac{\lambda+2\mu}{\rho}}$ is the P-wave velocity and $\beta = \sqrt{\frac{\mu}{\rho}}$ is the S-wave velocity.

Displacement U at $z = 2, t = 200$ Displacement U at $z = 2, t = 500$ Displacement U at $z = 2, t = 1000$ Displacement U at $z = 2, t = 1500$ 

Displacement U at $z = 2, t = 200$ Displacement U at $z = 2, t = 500$ Displacement U at $z = 2, t = 1000$ Displacement U at $z = 2, t = 1500$ 

Questions

Moczo, P., Kristek, J., Galis, M., Pazak, P., Balazovjech, M. The finite difference and finite element modeling of seismic wave propagation and earthquake motion. *Acta Physica Slovaca*, 57(2):177-406, April 2007.

Bormann, P., Engdahl, B., Kind, R. Seismic Wave Propagation and Earth Models. In: Bormann, P. (Ed.) *New Manual of Seismological Observatory Practice (NMSOP)* Postdam: Deutsches Geo-Forschungs Zentrum GFZ, 2009.