

Symbolic Computation of Exact Solutions of Nonlinear Wave Equations

Willy Hereman
Colorado School of Mines
Golden, CO 80401

in collaboration with Wuning Zhuang

Rocky Mountain Nonlinear Experience
Mini Symposium, Program in Applied Mathematics
University of Colorado at Boulder
August 12 & 13, 1991

I. INTRODUCTION

Symbolic Software for Soliton Theory

- Painlevé test for single ODE or PDE
- Lie symmetries of systems of PDEs
- Solitary wave solutions via real exponential approach
- Test for and construction of soliton solutions via Hirota's method

All the above programs are written in MACSYMA

- Hirota's Direct Method
 - allows to construct exact soliton solutions of
 - nonlinear evolution equations
 - wave equations
 - coupled systems
- Conditions for existence of soliton solutions (integrability)
- Algorithm
- MACSYMA implementation
- Syntax of the Code
- Examples:
 - Korteweg-de Vries equation (KdV)
 - Kadomtsev-Petviashvili equation (KP)
 - Sawada-Kotera equation (SK)
- Single equation
- Coupled system (two equations): work in progress

II. HIROTA'S METHOD

Hirota's method requires:

- a clever change of dependent variable
- the introduction of a novel differential operator
- a perturbation expansion to solve the resulting bilinear equation

Korteweg-de Vries equation

$$u_t + 6uu_x + u_{3x} = 0$$

Substitute

$$u(x, t) = 2 \frac{\partial^2 \ln f(x, t)}{\partial x^2}$$

Integrate with respect to x

$$f f_{xt} - f_x f_t + f f_{4x} - 4f_x f_{3x} + 3f_{2x}^2 = 0$$

Bilinear form

$$B(f \cdot f) \stackrel{\text{def}}{=} (D_x D_t + D_x^4) (f \cdot f) = 0$$

New operator

$$D_x^m D_t^n (f \cdot g) = (\partial x - \partial x')^m (\partial t - \partial t')^n f(x, t) g(x', t')|_{x'=x, t'=t}$$

Expansion

$$f = 1 + \sum_{n=1}^{\infty} \epsilon^n f_n$$

Substitute f into the bilinear equation

Collect powers in ϵ (book keeping parameter)

$$O(\epsilon^0) : B(1 \cdot 1) = 0$$

$$O(\epsilon^1) : B(1 \cdot f_1 + f_1 \cdot 1) = 0$$

$$O(\epsilon^2) : B(1 \cdot f_2 + f_1 \cdot f_1 + f_2 \cdot 1) = 0$$

$$O(\epsilon^3) : B(1 \cdot f_3 + f_1 \cdot f_2 + f_2 \cdot f_1 + f_3 \cdot 1) = 0$$

$$O(\epsilon^4) : B(1 \cdot f_4 + f_1 \cdot f_3 + f_2 \cdot f_2 + f_3 \cdot f_1 + f_4 \cdot 1) = 0$$

$$O(\epsilon^n) : B\left(\sum_{j=0}^n f_j \cdot f_{n-j}\right) = 0 \quad \text{with } f_0 = 1$$

If the original PDE admits a N-soliton solution then the expansion will truncate at level $n = N$ provided

$$f_1 = \sum_{i=1}^N \exp(\theta_i) = \sum_{i=1}^N \exp(k_i x - \omega_i t + \delta_i)$$

k_i, ω_i and δ_i are constants

Dispersion law

$$\omega_i = k_i^3 \quad i = 1, 2, \dots, N$$

Consider the case $N=3$

Terms generated by $B(f_1, f_1)$ justify

$$\begin{aligned} f_2 &= a_{12} \exp(\theta_1 + \theta_2) + a_{13} \exp(\theta_1 + \theta_3) + a_{23} \exp(\theta_2 + \theta_3) \\ &= a_{12} \exp[(k_1 + k_2)x - (\omega_1 + \omega_2)t + (\delta_1 + \delta_2)] \\ &\quad + a_{13} \exp[(k_1 + k_3)x - (\omega_1 + \omega_3)t + (\delta_1 + \delta_3)] \\ &\quad + a_{23} \exp[(k_2 + k_3)x - (\omega_2 + \omega_3)t + (\delta_2 + \delta_3)] \end{aligned}$$

Allows to calculate the constants a_{12}, a_{13} and a_{23}

One obtains

$$a_{ij} = \frac{(k_i - k_j)^2}{(k_i + k_j)^2} \quad i, j = 1, 2, 3$$

$B(f_1 \cdot f_2 + f_2 \cdot f_1)$ motivates

$$\begin{aligned} f_3 &= b_{123} \exp(\theta_1 + \theta_2 + \theta_3) \\ &= b_{123} \exp[(k_1 + k_2 + k_3)x - (\omega_1 + \omega_2 + \omega_3)t + (\delta_1 + \delta_2 + \delta_3)] \end{aligned}$$

with

$$b_{123} = a_{12} a_{13} a_{23} = \frac{(k_1 - k_2)^2 (k_1 - k_3)^2 (k_2 - k_3)^2}{(k_1 + k_2)^2 (k_1 + k_3)^2 (k_2 + k_3)^2}$$

Subsequently, $f_i = 0$ for $i > 3$

Set $\epsilon = 1$

$$\begin{aligned} f &= 1 + \exp \theta_1 + \exp \theta_2 + \exp \theta_3 \\ &+ a_{12} \exp(\theta_1 + \theta_2) + a_{13} \exp(\theta_1 + \theta_3) + a_{23} \exp(\theta_2 + \theta_3) \\ &+ b_{123} \exp(\theta_1 + \theta_2 + \theta_3) \end{aligned}$$

Return to the original $u(x, t)$

$$u(x, t) = 2 \frac{\partial^2 \ln f(x, t)}{\partial x^2}$$

III. Hirota conditions

Bilinear equation

$$P(D_x, D_t)f \cdot f = 0$$

P is an arbitrary polynomial

- Single soliton solution

$$f = 1 + e^\theta, \quad \theta = kx - \omega t + \delta$$

k, ω and δ are constants

k and ω satisfy the dispersion law

$$P(k, -\omega) = 0$$

- Two soliton solution

$$f = 1 + e^{\theta_1} + e^{\theta_2} + a_{12}e^{\theta_1 + \theta_2}$$

$$\theta_i = k_i x - \omega_i t + \delta_i, \quad P(k_i, -\omega_i) = 0 \quad i = 1, 2$$

$$a_{12} = -\frac{P(k_1 - k_2, -\omega_1 + \omega_2)}{P(k_1 + k_2, -\omega_1 - \omega_2)}$$

If a bilinear form is available then the equation always has at least a two-soliton solution provided

$$* P(0, 0) = 0 \quad \text{no constant term}$$

$$* P(k, \omega) = P(-k, -\omega) \quad P \text{ is even}$$

- For the general N-soliton solution

$$f = \sum_{\mu=0,1} \exp\left[\sum_{i>j}^{(N)} A_{ij} \mu_i \mu_j + \sum_{i=1}^N \mu_i \theta_i\right]$$

$$a_{ij} = \exp A_{ij} = -\frac{P(k_i - k_j, -\omega_i + \omega_j)}{P(k_i + k_j, -\omega_i - \omega_j)}$$

$$\begin{aligned} S[P, n] &= \sum_{\sigma=\pm 1} P\left(\sum_{i=1}^n \sigma_i k_{s_i}, -\sum_{i=1}^n \sigma_i \omega_{s_i}\right) \\ &\times \prod_{i>j}^{(n)} (\sigma_i k_{s_i} - \sigma_j k_{s_j}, -\sigma_i \omega_{s_i} + \sigma_j \omega_{s_j}) \sigma_i \sigma_j = 0 \end{aligned}$$

$$n = 1, \dots, N. \quad s_i \in \{1, \dots, N\}, \quad k_i > k_j, \quad i > j$$

IV. ALGORITHM FOR THE HIROTA METHOD

- Blocks (functions)

- Block 1: Dispersion law

$$B(1 \cdot f_1 + f_1 \cdot 1) = 0$$

- Block 2: Test the conditions for 2 or 3 soliton solution
- Block 3: Construct a N -soliton solution ($N = 1, 2, 3$)
- Block 4: Check two soliton solution (polynomials)
- Block 5: Check three soliton solution (polynomials)
- Block 6: Hirota operators D_x, D_y, D_t, D_{xt}
- Block 7: Hirota's method

- Main Program

Hirota(B,name,n,test_for_3soliton,
check_coefficients,test_for_4soliton)

$B(f, g)$: Bilinear operator for the PDE

name: Name of the PDE

n: N-soliton solution

test_for_3soliton: True or false for the testing the Hirota conditions

check_coefficients: True or false for checking the calculated coefficients of the 2 and 3 soliton solutions

test_for_4soliton: True or false for the testing the Hirota conditions

V. MACSYMA PROGRAM

The symbolic program calculates

- the one soliton solution
- checks conditions for a 3 or even a 4 soliton solution
- constructs the two and three soliton solutions
- recalculates a_{ij} based on the polynomial form P
- verifies if $b_{123} = a_{12}a_{13}a_{23}$

The user must

- select the value of N
- provide the bilinear operator B
- give a name for the PDE
- set true or false for ‘test_for_3soliton’, ‘check_coefficients’ and ‘test_for_4soliton’

VI. EXAMPLES AND TEST CASES

- Korteweg-de Vries equation

$$u_t + 6uu_x + u_{3x} = 0$$

One uses

$$u(x, t) = 2 \frac{\partial^2 \ln f(x, t)}{\partial x^2}$$

$$B(f, g) := Dxt[1, 1](f, g) + Dx[4](f, g)$$

One obtains

$$\omega_i = k_i^3, \quad i = 1, 2, 3$$

and

$$a_{ij} = \frac{(k_i - k_j)^2}{(k_i + k_j)^2}, \quad i, j = 1, 2, 3 \quad i > j$$

$$b_{123} = a_{12}a_{13}a_{23}$$

There also exists a four soliton solution

- Kadomtsev-Petviashvili equation

$$(u_t + 6uu_x + u_{3x})_x + 3u_{2y} = 0$$

Here

$$u(x, t) = 2 \frac{\partial^2 \ln f(x, y, t)}{\partial x^2}$$

$$B(f, g) := Dxt[1, 1](f, g) + Dx[4](f, g) + 3Dy[2](f, g)$$

In this case $\theta_i = k_i x + l_i y - \omega_i t$

$$\omega_i = \frac{3l_i^2 + k_i^4}{k_i}, \quad i = 1, 2, 3$$

and

$$a_{ij} = \frac{(k_i k_j^2 - k_i^2 k_j - l_i k_j + l_j k_i)(k_i k_j^2 - k_i^2 k_j + l_i k_j - l_j k_i)}{(k_i k_j^2 + k_i^2 k_j + l_i k_j - l_j k_i)(k_i k_j^2 + k_i^2 k_j - l_i k_j + l_j k_i)}$$

$$b_{123} = a_{12}a_{13}a_{23}$$

There also exists a four soliton solution

- Sawada-Kotera equation

$$u_t + 45u^2u_x + 15u_xu_{2x} + 15uu_{3x} + u_{5x} = 0$$

One uses

$$u(x, t) = 2 \frac{\partial^2 \ln f(x, t)}{\partial x^2}$$

and

$$B(f, g) := Dxt[1, 1](f, g) + Dx[6](f, g)$$

Furthermore

$$\omega_i = k_i^5, \quad i = 1, 2, 3$$

$$a_{ij} = \frac{(k_i - k_j)^3 (k_i^3 + k_j^3)}{(k_i + k_j)^3 (k_i^3 - k_j^3)}, \quad i, j = 1, 2, 3$$

$$b_{123} = a_{12}a_{13}a_{23}$$

There also exists a four soliton solution

REFERENCES

- [1] R. Hirota, in: *Bäcklund Transformations, the Inverse Scattering Method, Solitons, and Their Applications*, Lecture Notes in Mathematics **515**, ed. R.M. Miura, Springer-Verlag, Berlin, 1976, pp. 40-68.
- [2] R. Hirota, in: *Solitons*, Topics in Physics **17**, eds. R.K. Bullough and P.J. Caudrey, Springer-Verlag, Berlin, 1980, pp. 157-76.
- [3] M.J. Ablowitz and H. Segur, *Solitons and the Inverse Scattering*, SIAM Studies in Applied Mathematics **4**, SIAM, Philadelphia, 1981.
- [4] P.G. Drazin and R.S. Johnson, *Solitons: an introduction*, Cambridge University Press, Cambridge, 1989.
- [5] J. Hietarinta, *A search for bilinear equations passing Hirota's three-soliton condition*, Parts I-IV, J. Math. Phys. **28**, 1732-42, 1987; *ibid.* 2094-101, 1987; *ibid.* 2586-92, 1987; *ibid.* **29** 628-35, 1988.

- [6] J. Hietarinta, in: *Partially Integrable Evolution Equations in Physics*, Proceedings of the Summer School for Theoretical Physics, Les Houches, France, March 21-28, 1989, eds: R. Conte and N. Boccara, Kluwer Academic Publishers, pp. 459-78, 1990.