To be more general, consider: L= dx+ + a dx + b => Ly(x)=f(x) w/ x ∈ (-10, 00) Now let's assume that fixi, yixi and dx all to for IXI to. Therefore we can do Fourier transforms of each: 1 (α-ik) dy eikx dx + f (ω b y (x)e dx = √ - ω f (x)e ikx dx

i.b. ρ. s again: [yeikx] - ω - ik ∫ ω ye kx dx = - ik ∫ ω y e dx So in the end we have:  $\begin{bmatrix}
-(a-ik):k+b \end{bmatrix} \xrightarrow{\frac{1}{2\pi}} \int_{-\infty}^{\infty} \gamma(x)e^{-ikx} dx = \frac{1}{\sqrt{2\pi}} \int_{-\infty}^{\infty} f(x)e^{-ikx} dx$   $\frac{\hat{\gamma}(k)}{\hat{\gamma}(k)} = \hat{f}(k) = \hat{\gamma}(k) = \frac{\hat{f}(k)}{-k^2 - iak + b}$ The surfaces on R' If underson F.T. on U undoing F.T. on Y y(x) = 1/17 ) = f(k) = ikx dk U undoing F.T. on f  $\gamma(x) = \frac{1}{1-1} \int_{-\infty}^{\infty} dx' \int_{-\infty}^{\infty} dk \frac{f(x)e^{ikx'}}{-k^4 - iak + b} e^{-ikx} \int_{-\infty}^{\infty} G(x,x')f(x')dx'$ Therefore:

G(x,x') = 1/11 \( \int\_{-\overline{k}}^{\infty} \frac{e}{-k^{\frac{1}{2}} \cdot ak + \int ak + To do the integral we resort to the results of the last chapter. Consider the contour:  $\frac{-12}{12} = -\frac{1}{2\pi i} \left\{ \frac{e^{-ik(x-x')}}{(k-k_{+})(k-k_{-})} dk \right\} = -\frac{1}{2\pi i} \left\{ \frac{e^{-ik(x-x')}}{(k-k_{+})(k-k_{-})$ Note that the limit as R-200 of this is what we want. Tringt of all: & (K-K+1(K-1C)) dk = 2 Ti (R++R-) where R± is the vesidue coming from k±. R = = 2 = (k-K =) dk where C + includes k + but not k = (hence the numerator is analytic)

Using (IF: 
$$\omega(z_0) = \frac{1}{4\pi i} \frac{1}{6} \frac{\omega(z_0)}{z-2a} dz$$

when  $\frac{1}{4\pi i} \frac{1}{4\pi i} = \frac{1}{4\pi i} \frac{1}{6\pi i} \frac{1}{4\pi i} \frac{1}{4\pi$ 

Lecture 23- Green and Dirac walk into a Delta Online Page 2

Now let's translate: dix+ + a dx + b y(x) = f(x) = y(x) - x(t), a = 28, b = w. y(x) = Ay, (x) + By, (x) + 1 = e= = (x-x') Sin [ ] = = (x-x') f(x')dx'  $x(t) = Ax_{1}(t) + (3x_{1}(t) + ) = \frac{e^{-Y(t-t')}}{\int_{w_{0}^{1}-Y^{2}}} \sin \left[ \int_{w_{0}^{1}-Y^{1}} (t-t') \right] F(t') dt'$ Which softisties:  $\frac{d^{2}x}{dt^{2}} + \frac{d^{2}x}{dt} + \omega_{0}^{2}X(t) = F(t) + \text{the equation for a forced and damped harrowic oscillator}$ Let  $F(t) = \begin{cases} 0 & t < 0 \\ Foe^{-yt} & t \ge 0 \end{cases}$  and assume it is at rest in equilibrium at  $t = 0 \Rightarrow A = B = 0$ Then: x(t) = \( \frac{e^{-\gamma(k-t')}}{\infty} \sin \left[ \int\_{\omega\_0}^{\omega\_0} - \gamma^{\text{t}} \left( (t-t') \right] \int\_{\omega\_0} \int\_{\omega\_0}^{\omega\_0} \delta^{\text{t}} = Foe - Yt ( 1 - 1) = (8-x)t' dt' Integration skills to the rescue! First consider: la x'e xx, how could you approach this? 1-low about IBP?  $\frac{1}{1k} \int_{a}^{b} x^{2} k e^{kx} dx = \frac{1}{k} \left[ x^{2} e^{kx} \right]_{a}^{b} - \frac{1}{k} \underbrace{\int_{a}^{b} x e^{kx} dx}_{k}^{k} = \frac{1}{k} \left[ x^{2} e^{kx} \right]_{a}^{b} - \frac{1}{k} \underbrace{\int_{a}^{b} x e^{kx} dx}_{k}^{k} = \frac{1}{k} \underbrace{\int_{a}^{b} x e^{kx} dx}_{k}^{b} = \frac{1}{k} \underbrace{\int_{a}^{b} x e^{kx} dx}_{k}^{b$ Now what about: ) six (wx) e dx, how about IBP? Six(wx) doesn't go away, but.  $\frac{1}{k}\int_{a}^{b} \frac{1}{5!} \wedge (\omega x) k e^{kx} dx = \frac{1}{k} \left[ \frac{1}{5!} \wedge (\omega x) e^{kx} \right]_{a}^{b} - \frac{\omega}{k} \int_{a}^{b} \frac{1}{5!} \wedge (\omega x) e^{kx} dx$   $= \frac{1}{k} \int_{a}^{b} \frac{1}{5!} \wedge (\omega x) e^{kx} dx$   $= \frac{1}{k} \int_{a}^{b} \frac{1}{5!} \wedge (\omega x) e^{kx} dx$   $= \frac{1}{k} \int_{a}^{b} \frac{1}{5!} \wedge (\omega x) e^{kx} dx$   $= \frac{1}{k} \int_{a}^{b} \frac{1}{5!} \wedge (\omega x) e^{kx} dx$   $= \frac{1}{k} \int_{a}^{b} \frac{1}{5!} \wedge (\omega x) e^{kx} dx$   $= \frac{1}{k} \int_{a}^{b} \frac{1}{5!} \wedge (\omega x) e^{kx} dx$   $= \frac{1}{k} \int_{a}^{b} \frac{1}{5!} \wedge (\omega x) e^{kx} dx$   $= \frac{1}{k} \int_{a}^{b} \frac{1}{5!} \wedge (\omega x) e^{kx} dx$   $= \frac{1}{k} \int_{a}^{b} \frac{1}{5!} \wedge (\omega x) e^{kx} dx$   $= \frac{1}{k} \int_{a}^{b} \frac{1}{5!} \wedge (\omega x) e^{kx} dx$   $= \frac{1}{k} \int_{a}^{b} \frac{1}{5!} \wedge (\omega x) e^{kx} dx$   $= \frac{1}{k} \int_{a}^{b} \frac{1}{5!} \wedge (\omega x) e^{kx} dx$   $= \frac{1}{k} \int_{a}^{b} \frac{1}{5!} \wedge (\omega x) e^{kx} dx$   $= \frac{1}{k} \int_{a}^{b} \frac{1}{5!} \wedge (\omega x) e^{kx} dx$   $= \frac{1}{k} \int_{a}^{b} \frac{1}{5!} \wedge (\omega x) e^{kx} dx$   $= \frac{1}{k} \int_{a}^{b} \frac{1}{5!} \wedge (\omega x) e^{kx} dx$   $= \frac{1}{k} \int_{a}^{b} \frac{1}{5!} \wedge (\omega x) e^{kx} dx$   $= \frac{1}{k} \int_{a}^{b} \frac{1}{5!} \wedge (\omega x) e^{kx} dx$   $= \frac{1}{k} \int_{a}^{b} \frac{1}{5!} \wedge (\omega x) e^{kx} dx$   $= \frac{1}{k} \int_{a}^{b} \frac{1}{5!} \wedge (\omega x) e^{kx} dx$   $= \frac{1}{k} \int_{a}^{b} \frac{1}{5!} \wedge (\omega x) e^{kx} dx$   $= \frac{1}{k} \int_{a}^{b} \frac{1}{5!} \wedge (\omega x) e^{kx} dx$   $= \frac{1}{k} \int_{a}^{b} \frac{1}{5!} \wedge (\omega x) e^{kx} dx$   $= \frac{1}{k} \int_{a}^{b} \frac{1}{5!} \wedge (\omega x) e^{kx} dx$   $= \frac{1}{k} \int_{a}^{b} \frac{1}{5!} \wedge (\omega x) e^{kx} dx$   $= \frac{1}{k} \int_{a}^{b} \frac{1}{5!} \wedge (\omega x) e^{kx} dx$   $= \frac{1}{k} \int_{a}^{b} \frac{1}{5!} \wedge (\omega x) e^{kx} dx$  $\frac{1}{1} \lim_{x \to \infty} \int_{a}^{b} \frac{1}{1} \int_{a}^{b}$ 

Using (a slightly modified version of) this, and employing some trig, the result can be written as:

Taking the dampening to zero 
$$(Y \rightarrow 0)$$
 we have:  $X(t) = \frac{\Gamma_0}{\omega_0} \frac{\sin \left[\omega_0 t - 8\right]}{\int \omega_0^1 + \omega_0^1} + \frac{\Gamma_0}{\omega_0^1 + \omega_0^1} = \frac{\sin \left[\omega_0 t - 8\right]}{\int \omega_0^1 + \omega_0^1} \times \frac{\sin \left[\omega_0 t - 8\right]}{\int \omega_0^1 + \omega_0^1} \times \frac{\sin \left[\omega_0 t - 8\right]}{\int \omega_0^1 + \omega_0^1} \times \frac{\sin \left[\omega_0 t - 8\right]}{\int \omega_0^1 + \omega_0^1} \times \frac{\sin \left[\omega_0 t - 8\right]}{\int \omega_0^1 + \omega_0^1} \times \frac{\sin \left[\omega_0 t - 8\right]}{\int \omega_0^1 + \omega_0^1} \times \frac{\sin \left[\omega_0 t - 8\right]}{\int \omega_0^1 + \omega_0^1} \times \frac{\sin \left[\omega_0 t - 8\right]}{\int \omega_0^1 + \omega_0^1} \times \frac{\sin \left[\omega_0 t - 8\right]}{\int \omega_0^1 + \omega_0^1} \times \frac{\sin \left[\omega_0 t - 8\right]}{\int \omega_0^1 + \omega_0^1} \times \frac{\sin \left[\omega_0 t - 8\right]}{\int \omega_0^1 + \omega_0^1} \times \frac{\sin \left[\omega_0 t - 8\right]}{\int \omega_0^1 + \omega_0^1} \times \frac{\sin \left[\omega_0 t - 8\right]}{\int \omega_0^1 + \omega_0^1} \times \frac{\sin \left[\omega_0 t - 8\right]}{\int \omega_0^1 + \omega_0^1} \times \frac{\sin \left[\omega_0 t - 8\right]}{\int \omega_0^1 + \omega_0^1} \times \frac{\sin \left[\omega_0 t - 8\right]}{\int \omega_0^1 + \omega_0^1} \times \frac{\sin \left[\omega_0 t - 8\right]}{\int \omega_0^1 + \omega_0^1} \times \frac{\sin \left[\omega_0 t - 8\right]}{\int \omega_0^1 + \omega_0^1} \times \frac{\sin \left[\omega_0 t - 8\right]}{\int \omega_0^1 + \omega_0^1} \times \frac{\sin \left[\omega_0 t - 8\right]}{\int \omega_0^1 + \omega_0^1} \times \frac{\sin \left[\omega_0 t - 8\right]}{\int \omega_0^1 + \omega_0^1} \times \frac{\sin \left[\omega_0 t - 8\right]}{\int \omega_0^1 + \omega_0^1} \times \frac{\sin \left[\omega_0 t - 8\right]}{\int \omega_0^1 + \omega_0^1} \times \frac{\sin \left[\omega_0 t - 8\right]}{\int \omega_0^1 + \omega_0^1} \times \frac{\sin \left[\omega_0 t - 8\right]}{\int \omega_0^1 + \omega_0^1} \times \frac{\sin \left[\omega_0 t - 8\right]}{\int \omega_0^1 + \omega_0^1} \times \frac{\sin \left[\omega_0 t - 8\right]}{\int \omega_0^1 + \omega_0^1} \times \frac{\sin \left[\omega_0 t - 8\right]}{\int \omega_0^1 + \omega_0^1} \times \frac{\sin \left[\omega_0 t - 8\right]}{\int \omega_0^1 + \omega_0^1} \times \frac{\sin \left[\omega_0 t - 8\right]}{\int \omega_0^1 + \omega_0^1} \times \frac{\sin \left[\omega_0 t - 8\right]}{\int \omega_0^1 + \omega_0^1} \times \frac{\sin \left[\omega_0 t - 8\right]}{\int \omega_0^1 + \omega_0^1} \times \frac{\sin \left[\omega_0 t - 8\right]}{\int \omega_0^1 + \omega_0^1} \times \frac{\sin \left[\omega_0 t - 8\right]}{\int \omega_0^1 + \omega_0^1} \times \frac{\sin \left[\omega_0 t - 8\right]}{\int \omega_0^1 + \omega_0^1} \times \frac{\sin \left[\omega_0 t - 8\right]}{\int \omega_0^1 + \omega_0^1} \times \frac{\sin \left[\omega_0 t - 8\right]}{\int \omega_0^1 + \omega_0^1} \times \frac{\sin \left[\omega_0 t - 8\right]}{\int \omega_0^1 + \omega_0^1} \times \frac{\sin \left[\omega_0 t - 8\right]}{\int \omega_0^1 + \omega_0^1} \times \frac{\sin \left[\omega_0 t - 8\right]}{\int \omega_0^1 + \omega_0^1} \times \frac{\sin \left[\omega_0 t - 8\right]}{\int \omega_0^1 + \omega_0^1} \times \frac{\sin \left[\omega_0 t - 8\right]}{\int \omega_0^1 + \omega_0^1} \times \frac{\sin \left[\omega_0 t - 8\right]}{\int \omega_0^1 + \omega_0^1} \times \frac{\sin \left[\omega_0 t - 8\right]}{\int \omega_0^1 + \omega_0^1} \times \frac{\sin \left[\omega_0 t - 8\right]}{\int \omega_0^1 + \omega_0^1} \times \frac{\sin \left[\omega_0 t - 8\right]}{\int \omega_0^1 + \omega_0^1} \times \frac{\sin \left[\omega_0 t - 8\right]}{\int \omega_0^1 + \omega_0^1} \times \frac{\sin \left[\omega_0 t - 8\right]}{\int \omega_0^1 + \omega_0^1} \times \frac{\sin \left[\omega_0 t - 8\right]}{\int \omega_0^1 + \omega_0^1} \times \frac{\sin \left[\omega_0 t - 8\right]}{\int \omega_0^1 + \omega_0^1} \times \frac{\sin \left[\omega_0 t - 8$ 

Now remember the spirit of Green's functions: They let you solve Ly(x) = f(x) by finding what is essentially the inverse of L, i.e. LG(x,x') = S(x,x'). The inverse does not depend on f(x), so once we have it, we can apply it to the equation w(any f(x)). It does depend on the boundary conditions, i.e. for Indoorder L we could use y(0), y'(0) or y(0), y(1).

But even more so, consider Ly(x) = f(x,y), which connot be easily manipulated into an integral equation for y(x). Or can it? y(x) = ) G(x,x') f[x', y(x')]dx'

So Green's help turn differential equations into integral equations.

Now in 10, there is actually on approach to finding to by solving LG(x,x') = S(x-x') directly for a given L. This process can be applied to operaters of arbitrary order. This doesn't actually work in higher dimensions, so we won't worry about it.