

Problem 4.2

- (a) Equation 4.8 $\Rightarrow -\frac{\hbar^2}{2m} \left(\frac{\partial^2 \psi}{\partial x^2} + \frac{\partial^2 \psi}{\partial y^2} + \frac{\partial^2 \psi}{\partial z^2} \right) = E\psi$ (inside the box). Separable solutions: $\psi(x, y, z) = X(x)Y(y)Z(z)$. Put this in, and divide by XYZ :

$$\frac{1}{X} \frac{d^2 X}{dx^2} + \frac{1}{Y} \frac{d^2 Y}{dy^2} + \frac{1}{Z} \frac{d^2 Z}{dz^2} = -\frac{2m}{\hbar^2} E.$$

The three terms on the left are functions of x , y , and z , respectively, so each must be a constant. Call the separation constants k_x^2 , k_y^2 , and k_z^2 (as we'll soon see, they must be positive).

$$\frac{d^2 X}{dx^2} = -k_x^2 X; \quad \frac{d^2 Y}{dy^2} = -k_y^2 Y; \quad \frac{d^2 Z}{dz^2} = -k_z^2 Z, \quad \text{with} \quad E = \frac{\hbar^2}{2m} (k_x^2 + k_y^2 + k_z^2).$$

Solution:

$$X(x) = A_x \sin k_x x + B_x \cos k_x x; \quad Y(y) = A_y \sin k_y y + B_y \cos k_y y; \quad Z(z) = A_z \sin k_z z + B_z \cos k_z z.$$

But $X(0) = 0$, so $B_x = 0$; $Y(0) = 0$, so $B_y = 0$; $Z(0) = 0$, so $B_z = 0$. And $X(a) = 0 \Rightarrow \sin(k_x a) = 0 \Rightarrow k_x = n_x \pi/a$ ($n_x = 1, 2, 3, \dots$). [As before (page 31), $n_x \neq 0$, and negative values are redundant.] Likewise $k_y = n_y \pi/a$ and $k_z = n_z \pi/a$. So

$$\psi(x, y, z) = A_x A_y A_z \sin\left(\frac{n_x \pi}{a} x\right) \sin\left(\frac{n_y \pi}{a} y\right) \sin\left(\frac{n_z \pi}{a} z\right), \quad E = \frac{\hbar^2 \pi^2}{2m a^2} (n_x^2 + n_y^2 + n_z^2).$$

We might as well normalize X , Y , and Z separately: $A_x = A_y = A_z = \sqrt{2/a}$. *Conclusion:*

$$\psi(x, y, z) = \left(\frac{2}{a}\right)^{3/2} \sin\left(\frac{n_x \pi}{a} x\right) \sin\left(\frac{n_y \pi}{a} y\right) \sin\left(\frac{n_z \pi}{a} z\right); \quad E = \frac{\pi^2 \hbar^2}{2m a^2} (n_x^2 + n_y^2 + n_z^2); \quad n_x, n_y, n_z = 1, 2, 3, \dots$$

(b)

n_x	n_y	n_z	$(n_x^2 + n_y^2 + n_z^2)$
1	1	1	3
1	1	2	6
1	2	1	6
2	1	1	6
1	2	2	9
2	1	2	9
2	2	1	9
1	1	3	11
1	3	1	11
3	1	1	11
2	2	2	12
1	2	3	14
1	3	2	14
2	1	3	14
2	3	1	14
3	1	2	14
3	2	1	14

Energy	Degeneracy
$E_1 = 3 \frac{\pi^2 \hbar^2}{2ma^2};$	$d = 1$
$E_2 = 6 \frac{\pi^2 \hbar^2}{2ma^2};$	$d = 3.$
$E_3 = 9 \frac{\pi^2 \hbar^2}{2ma^2};$	$d = 3.$
$E_4 = 11 \frac{\pi^2 \hbar^2}{2ma^2};$	$d = 3.$
$E_5 = 12 \frac{\pi^2 \hbar^2}{2ma^2};$	$d = 1.$
$E_6 = 14 \frac{\pi^2 \hbar^2}{2ma^2};$	$d = 6.$

(c) The next combinations are: $E_7(322)$, $E_8(411)$, $E_9(331)$, $E_{10}(421)$, $E_{11}(332)$, $E_{12}(422)$, $E_{13}(431)$, and $E_{14}(333$ and $511)$. The degeneracy of E_{14} is $\boxed{4}$. Simple combinatorics accounts for degeneracies of 1 ($n_x = n_y = n_z$), 3 (two the same, one different), or 6 (all three different). But in the case of E_{14} there is a numerical "accident": $3^2 + 3^2 + 3^2 = 27$, but $5^2 + 1^2 + 1^2$ is *also* 27, so the degeneracy is greater than combinatorial reasoning alone would suggest.

Problem 4.3

$$\text{Eq. 4.32} \Rightarrow Y_0^0 = \frac{1}{\sqrt{4\pi}} P_0^0(\cos \theta); \text{ Eq. 4.27} \Rightarrow P_0^0(x) = P_0(x); \text{ Eq. 4.28} \Rightarrow P_0(x) = 1. \quad \boxed{Y_0^0 = \frac{1}{\sqrt{4\pi}}}$$

$$Y_2^1 = -\sqrt{\frac{5}{4\pi}} \frac{1}{3 \cdot 2} e^{i\phi} P_2^1(\cos \theta); \quad P_2^1(x) = \sqrt{1-x^2} \frac{d}{dx} P_2(x);$$

$$P_2(x) = \frac{1}{4 \cdot 2} \left(\frac{d}{dx} \right)^2 (x^2 - 1)^2 = \frac{1}{8} \frac{d}{dx} [2(x^2 - 1)2x] = \frac{1}{2} [x^2 - 1 + x(2x)] = \frac{1}{2} (3x^2 - 1);$$

$$P_2^1(x) = \sqrt{1-x^2} \frac{d}{dx} \left[\frac{3}{2} x^2 - \frac{1}{2} \right] = \sqrt{1-x^2} 3x; \quad P_2^1(\cos \theta) = 3 \cos \theta \sin \theta. \quad \boxed{Y_2^1 = -\sqrt{\frac{15}{8\pi}} e^{i\phi} \sin \theta \cos \theta.}$$

$$\text{Normalization: } \iint |Y_0^0|^2 \sin \theta \, d\theta \, d\phi = \frac{1}{4\pi} \left[\int_0^\pi \sin \theta \, d\theta \right] \left[\int_0^{2\pi} d\phi \right] = \frac{1}{4\pi} (2)(2\pi) = 1. \quad \checkmark$$

$$\begin{aligned} \iint |Y_2^1|^2 \sin \theta \, d\theta \, d\phi &= \frac{15}{8\pi} \int_0^\pi \sin^2 \theta \cos^2 \theta \sin \theta \, d\theta \int_0^{2\pi} d\phi = \frac{15}{4} \int_0^\pi \cos^2 \theta (1 - \cos^2 \theta) \sin \theta \, d\theta \\ &= \frac{15}{4} \left[-\frac{\cos^3 \theta}{3} + \frac{\cos^5 \theta}{5} \right]_0^\pi = \frac{15}{4} \left[\frac{2}{3} - \frac{2}{5} \right] = \frac{5}{2} - \frac{3}{2} = 1 \quad \checkmark \end{aligned}$$

$$\text{Orthogonality: } \iint Y_0^0 Y_2^1 \sin \theta \, d\theta \, d\phi = -\frac{1}{\sqrt{4\pi}} \sqrt{\frac{15}{8\pi}} \left[\underbrace{\int_0^\pi \sin \theta \cos \theta \sin \theta \, d\theta}_{(\sin^3 \theta)/3 \Big|_0^\pi = 0} \right] \left[\underbrace{\int_0^{2\pi} e^{i\phi} d\phi}_{(e^{i\phi})/i \Big|_0^{2\pi} = 0} \right] = 0. \quad \checkmark$$

Problem 4.5

$$Y_l^l = (-1)^l \sqrt{\frac{(2l+1)!}{4\pi (2l)!}} e^{il\phi} P_l^l(\cos \theta). \quad P_l^l(x) = (1-x^2)^{l/2} \left(\frac{d}{dx} \right)^l P_l(x).$$

$$P_l(x) = \frac{1}{2^l l!} \left(\frac{d}{dx} \right)^l (x^2 - 1)^l. \quad \text{so } P_l^l(x) = \frac{1}{2^l l!} (1-x^2)^{l/2} \left(\frac{d}{dx} \right)^{2l} (x^2 - 1)^l.$$

Now $(x^2 - 1)^l = x^{2l} + \dots$, where all the other terms involve powers of x less than $2l$, and hence give zero when differentiated $2l$ times. So

$$P_l^l(x) = \frac{1}{2^l l!} (1-x^2)^{l/2} \left(\frac{d}{dx} \right)^{2l} x^{2l}. \quad \text{But } \left(\frac{d}{dx} \right)^n x^n = n!, \quad \text{so } P_l^l = \frac{(2l)!}{2^l l!} (1-x^2)^{l/2}.$$

$$\therefore Y_l^l = (-1)^l \sqrt{\frac{(2l+1)!}{4\pi (2l)!}} e^{il\phi} \frac{(2l)!}{2^l l!} (\sin \theta)^l = \boxed{\frac{1}{l!} \sqrt{\frac{(2l+1)!}{4\pi}} \left(-\frac{1}{2} e^{i\phi} \sin \theta \right)^l}.$$

$$Y_3^2 = \sqrt{\frac{7}{4\pi}} \cdot \frac{1}{5!} e^{2i\phi} P_3^2(\cos\theta); \quad P_3^2(x) = (1-x^2) \left(\frac{d}{dx}\right)^2 P_3(x); \quad P_3(x) = \frac{1}{8 \cdot 3!} \left(\frac{d}{dx}\right)^3 (x^2-1)^3.$$

$$\begin{aligned} P_3 &= \frac{1}{8 \cdot 3 \cdot 2} \left(\frac{d}{dx}\right)^2 [6x(x^2-1)^2] = \frac{1}{8} \frac{d}{dx} [(x^2-1)^2 + 4x^2(x^2-1)] \\ &= \frac{1}{8} [4x(x^2-1) + 8x(x^2-1) + 4x^2 \cdot 2x] = \frac{1}{2} (x^3 - x + 2x^3 - 2x + 2x^3) = \frac{1}{2} (5x^3 - 3x). \end{aligned}$$

$$P_3^2(x) = \frac{1}{2} (1-x^2) \left(\frac{d}{dx}\right)^2 (5x^3 - 3x) = \frac{1}{2} (1-x^2) \frac{d}{dx} (15x^2 - 3) = \frac{1}{2} (1-x^2) 30x = 15x(1-x^2).$$

$$Y_3^2 = \sqrt{\frac{7}{4\pi}} \frac{1}{5!} 15e^{2i\phi} \cos\theta \sin^2\theta = \boxed{\frac{1}{4} \sqrt{\frac{105}{2\pi}} e^{2i\phi} \sin^2\theta \cos\theta}.$$

Check that Y_l^t satisfies Eq. 4.18: Let $\frac{1}{l!} \sqrt{\frac{(2l+1)!}{4\pi}} \left(-\frac{1}{2}\right)^l = A$, so $Y_l^t = A(e^{i\phi} \sin\theta)^l$.

$$\frac{\partial Y_l^t}{\partial \theta} = A e^{2i\phi} l (\sin\theta)^{l-1} \cos\theta; \quad \sin\theta \frac{\partial Y_l^t}{\partial \theta} = l \cos\theta Y_l^t;$$

$$\sin\theta \frac{\partial}{\partial \theta} \left(\sin\theta \frac{\partial Y_l^t}{\partial \theta} \right) = l \cos\theta \left(\sin\theta \frac{\partial Y_l^t}{\partial \theta} \right) - l \sin^2\theta Y_l^t = (l^2 \cos^2\theta - l \sin^2\theta) Y_l^t. \quad \frac{\partial^2 Y_l^t}{\partial \phi^2} = -l^2 Y_l^t.$$

So the left side of Eq. 4.18 is $[l^2(1 - \sin^2\theta) - l \sin^2\theta - l^2] Y_l^t = -l(l+1) \sin^2\theta Y_l^t$, which matches the right side.

Check that Y_3^2 satisfies Eq. 4.18: Let $B = \frac{1}{4} \sqrt{\frac{105}{2\pi}}$, so $Y_3^2 = B e^{2i\phi} \sin^2\theta \cos\theta$.

$$\frac{\partial Y_3^2}{\partial \theta} = B e^{2i\phi} (2 \sin\theta \cos^2\theta - \sin^3\theta); \quad \sin\theta \frac{\partial}{\partial \theta} \left(\sin\theta \frac{\partial Y_3^2}{\partial \theta} \right) = B e^{2i\phi} \sin\theta \frac{\partial}{\partial \theta} (2 \sin^2\theta \cos^2\theta - \sin^4\theta)$$

$$= B e^{2i\phi} \sin\theta (4 \sin\theta \cos^3\theta - 4 \sin^3\theta \cos\theta - 4 \sin^3\theta \cos\theta) = 4 B e^{2i\phi} \sin^2\theta \cos\theta (\cos^2\theta - 2 \sin^2\theta)$$

$$= 4(\cos^2\theta - 2 \sin^2\theta) Y_3^2. \quad \frac{\partial^2 Y_3^2}{\partial \phi^2} = -4 Y_3^2. \quad \text{So the left side of Eq. 4.18 is}$$

$$4(\cos^2\theta - 2 \sin^2\theta - 1) Y_3^2 = 4(-3 \sin^2\theta) Y_3^2 = -l(l+1) \sin^2\theta Y_3^2,$$

where $l = 3$, so it fits the right side of Eq. 4.18.

Problem 4.11

(a)

$$\text{Eq. 4.31} \Rightarrow \int_0^\infty |R|^2 r^2 dr = 1. \quad \text{Eq. 4.82} \Rightarrow R_{20} = \left(\frac{c_0}{2a}\right) \left(1 - \frac{r}{2a}\right) e^{-r/2a}, \quad \text{Let } z \equiv \frac{r}{a}.$$

$$1 = \left(\frac{c_0}{2a}\right)^2 a^3 \int_0^\infty \left(1 - \frac{z}{2}\right)^2 e^{-z} z^2 dz = \frac{c_0^2 a}{4} \int_0^\infty \left(z^2 - z^3 + \frac{1}{4} z^4\right) e^{-z} dz = \frac{c_0^2 a}{4} \left(2 - 6 + \frac{24}{4}\right) = \frac{a}{2} c_0^2.$$

$$\therefore \boxed{c_0 = \sqrt{\frac{2}{a}}} \quad \text{Eq. 4.15} \Rightarrow \psi_{200} = R_{20} Y_0^0. \quad \text{Table 4.3} \Rightarrow Y_0^0 = \frac{1}{\sqrt{4\pi}}.$$

$$\therefore \psi_{200} = \frac{1}{\sqrt{4\pi}} \sqrt{\frac{2}{a}} \frac{1}{2a} \left(1 - \frac{r}{2a}\right) e^{-r/2a} \Rightarrow \boxed{\psi_{200} = \frac{1}{\sqrt{2\pi a}} \frac{1}{2a} \left(1 - \frac{r}{2a}\right) e^{-r/2a}}.$$

(b)

$$R_{21} = \frac{c_0}{4a^2} r e^{-r/2a}; \quad 1 = \left(\frac{c_0}{4a^2}\right)^2 a^5 \int_0^\infty z^4 e^{-z} dz = \frac{c_0^2 a}{16} 24 = \frac{3}{2} a c_0^2, \quad \text{so } \boxed{c_0 = \sqrt{\frac{2}{3a}}}.$$

$$R_{21} = \frac{1}{\sqrt{6a}} \frac{1}{2a^2} r e^{-r/2a}; \quad \psi_{211} = \frac{1}{\sqrt{6a}} \frac{1}{2a^2} r e^{-r/2a} \left(\mp \sqrt{\frac{3}{8\pi}} \sin \theta e^{\pm i\phi}\right) = \boxed{\mp \frac{1}{\sqrt{\pi a}} \frac{1}{8a^2} r e^{-r/2a} \sin \theta e^{\pm i\phi}};$$

$$\psi_{210} = \frac{1}{\sqrt{6a}} \frac{1}{2a^2} r e^{-r/2a} \left(\sqrt{\frac{3}{4\pi}} \cos \theta\right) = \boxed{\frac{1}{\sqrt{2\pi a}} \frac{1}{4a^2} r e^{-r/2a} \cos \theta}.$$

4.12 (c)

$$\text{Eq. 4.62} \Rightarrow v(\rho) = \sum_{j=0}^{\infty} c_j \rho^j, \quad \text{Eq. 4.76} \Rightarrow c_1 = \frac{2(3-5)}{(1)(6)} c_0 = -\frac{2}{3} c_0.$$

$$c_2 = \frac{2(4-5)}{(2)(7)} c_1 = -\frac{1}{7} c_1 = \frac{2}{21} c_0; \quad c_3 = \frac{2(5-5)}{(3)(8)} c_2 = 0.$$

$$v(\rho) = c_0 - \frac{2}{3} c_0 \rho + \frac{2}{21} c_0 \rho^2 = \boxed{\frac{c_0}{21} (21 - 14\rho + 2\rho^2)}. \quad \checkmark$$
