

Problem 4.12

(a)

$$L_0 = e^x e^{-x} = \boxed{1}, \quad L_1 = e^x \frac{d}{dx} (e^{-x} x) = e^x [e^{-x} - e^{-x} x] = \boxed{1 - x}.$$

$$\begin{aligned} L_2 &= e^x \left(\frac{d}{dx} \right)^2 (e^{-x} x^2) = e^x \frac{d}{dx} (2xe^{-x} - e^{-x} x^2) \\ &= e^x (2e^{-x} - 2xe^{-x} + e^{-x} x^2 - 2xe^{-x}) = \boxed{2 - 4x + x^2}. \end{aligned}$$

$$\begin{aligned} L_3 &= e^x \left(\frac{d}{dx} \right)^3 (e^{-x} x^3) = e^x \left(\frac{d}{dx} \right)^2 (-e^{-x} x^3 + 3x^2 e^{-x}) \\ &= e^x \frac{d}{dx} (e^{-x} x^3 - 3x^2 e^{-x} - 3x^2 e^{-x} + 6x e^{-x}) \\ &= e^x (-e^{-x} x^3 + 3x^2 e^{-x} + 6x^2 e^{-x} - 12x e^{-x} - 6x e^{-x} + 6e^{-x}) \\ &= \boxed{6 - 18x + 9x^2 - x^3}. \end{aligned}$$

(b)

$$v(\rho) = L_2^2(2\rho); \quad L_2^5(x) = L_{7-5}^2(x) = (-1)^5 \left(\frac{d}{dx} \right)^5 L_2(x).$$

$$\begin{aligned} L_7(x) &= e^x \left(\frac{d}{dx} \right)^7 (x^2 e^{-x}) = e^x \left(\frac{d}{dx} \right)^6 (7x^6 e^{-x} - x^7 e^{-x}) \\ &= e^x \left(\frac{d}{dx} \right)^5 (42x^5 e^{-x} - 7x^6 e^{-x} - 7x^6 e^{-x} + x^7 e^{-x}) \\ &= e^x \left(\frac{d}{dx} \right)^4 (210x^4 e^{-x} - 42x^5 e^{-x} - 84x^5 e^{-x} + 14x^6 e^{-x} + 7x^6 e^{-x} - x^7 e^{-x}) \\ &= e^x \left(\frac{d}{dx} \right)^3 \left[840x^3 e^{-x} - (210 + 630)x^4 e^{-x} \right. \\ &\quad \left. + (126 + 126)x^5 e^{-x} - (21 + 7)x^6 e^{-x} + x^7 e^{-x} \right] \\ &= e^x \left(\frac{d}{dx} \right)^2 (2520x^2 e^{-x} - (840 + 3360)x^3 e^{-x} \\ &\quad + (840 + 1260)x^4 e^{-x} - (252 + 168)x^5 e^{-x} + (28 + 7)x^6 e^{-x} - x^7 e^{-x}) \\ &= e^x \left(\frac{d}{dx} \right) \left[5040x e^{-x} - (2520 + 12600)x^2 e^{-x} + (4200 + 8400)x^3 e^{-x} \right. \\ &\quad \left. - (2100 + 2100)x^4 e^{-x} + (420 + 210)x^5 e^{-x} - (35 + 7)x^6 e^{-x} + x^7 e^{-x} \right] \\ &= e^x \left[5040e^{-x} - (5040 + 30240)xe^{-x} + (15120 + 37800)x^2 e^{-x} \right. \\ &\quad \left. - (12600 + 8400 + 8400)x^3 e^{-x} + (2100 + 2100 + 3150)x^4 e^{-x} \right. \\ &\quad \left. - (630 + 252)x^5 e^{-x} + (42 + 7)x^6 e^{-x} - x^7 e^{-x} \right] \\ &= 5040 - 35280x + 52920x^2 - 29400x^3 + 7350x^4 - 882x^5 + 49x^6 - x^7. \end{aligned}$$

$$\begin{aligned}
 L_z^5 &= - \left(\frac{d}{dx} \right)^5 (-882x^5 + 49x^6 - x^7) \\
 &= - [-882(5 \cdot 4 \cdot 3 \cdot 2) + 49(6 \cdot 5 \cdot 4 \cdot 3 \cdot 2)x - 7 \cdot 6 \cdot 5 \cdot 4 \cdot 3x^2] \\
 &= 60 [(882 \times 2) - (49 \times 12)x + 42x^2] = 2520(42 - 14x + x^2).
 \end{aligned}$$

$$v(\rho) = 2520(42 - 28\rho + 4\rho^2) = \boxed{5040(21 - 14\rho + 2\rho^2)}.$$

(c)

$$\text{Eq. 4.62} \Rightarrow v(\rho) = \sum_{j=0}^{\infty} c_j \rho^j, \quad \text{Eq. 4.76} \Rightarrow c_1 = \frac{2(3-5)}{(1)(6)} c_0 = -\frac{2}{3} c_0.$$

$$c_2 = \frac{2(1-5)}{(2)(7)} c_1 = -\frac{1}{7} c_1 = \frac{2}{21} c_0; \quad c_3 = \frac{2(5-5)}{(3)(8)} c_2 = 0.$$

$$v(\rho) = c_0 - \frac{2}{3} c_0 \rho + \frac{2}{21} c_0 \rho^2 = \boxed{\frac{c_0}{21} (21 - 14\rho + 2\rho^2)}. \quad \checkmark$$

Problem 4.13

(a)

$$\psi = \frac{1}{\sqrt{\pi a^3}} e^{-r/a}, \quad \text{so } \langle r^n \rangle = \frac{1}{\pi a^3} \int r^n e^{-2r/a} (r^2 \sin \theta \, dr \, d\theta \, d\phi) = \frac{4\pi}{\pi a^3} \int_0^{\infty} r^{n+2} e^{-2r/a} dr.$$

$$\langle r \rangle = \frac{4}{a^3} \int_0^{\infty} r^3 e^{-2r/a} dr = \frac{4}{a^3} 3! \left(\frac{a}{2} \right)^4 = \boxed{\frac{3}{2} a}; \quad \langle r^2 \rangle = \frac{4}{a^3} \int_0^{\infty} r^4 e^{-2r/a} dr = \frac{4}{a^3} 4! \left(\frac{a}{2} \right)^5 = \boxed{3a^2}.$$

(b)

$$\boxed{\langle x \rangle = 0}; \quad \langle x^2 \rangle = \frac{1}{3} \langle r^2 \rangle = \boxed{a^2}.$$

(c)

$$\psi_{211} = R_{21} Y_1^1 = -\frac{1}{\sqrt{\pi a}} \frac{1}{8a^2} r e^{-r/2a} \sin \theta e^{i\phi} \quad (\text{Problem 4.11(b)}).$$

$$\begin{aligned}
 \langle x^2 \rangle &= \frac{1}{\pi a} \frac{1}{(8a^2)^2} \int (r^2 e^{-r/a} \sin^2 \theta) (r^2 \sin^2 \theta \cos^2 \phi) r^2 \sin \theta \, dr \, d\theta \, d\phi \\
 &= \frac{1}{64\pi a^5} \int_0^{\infty} r^6 e^{-r/a} dr \int_0^{\pi} \sin^5 \theta \, d\theta \int_0^{2\pi} \cos^2 \phi \, d\phi \\
 &= \frac{1}{64\pi a^5} (6! a^7) \left(2 \frac{2 \cdot 4}{1 \cdot 3 \cdot 5} \right) \left(\frac{1}{2} \cdot 2\pi \right) = \boxed{12a^2}.
 \end{aligned}$$

Problem 4.18

$$\langle f | L_{\pm} g \rangle = \langle f | L_x g \rangle \pm i \langle f | L_y g \rangle = \langle L_x f | g \rangle \pm i \langle L_y f | g \rangle = \langle (L_x \mp i L_y) f | g \rangle = \langle L_{\mp} f | g \rangle, \text{ so } (L_{\pm})^\dagger = L_{\mp}.$$

Now, using Eq. 4.112, in the form $L_{\mp} L_{\pm} = L^2 - L_z^2 \mp \hbar L_z$:

$$\begin{aligned} \langle f_l^m | L_{\mp} L_{\pm} f_l^m \rangle &= \langle f_l^m | (L^2 - L_z^2 \mp \hbar L_z) f_l^m \rangle = \langle f_l^m | [\hbar^2 l(l+1) - \hbar^2 m^2 \mp \hbar^2 m] f_l^m \rangle \\ &= \hbar^2 [l(l+1) - m(m \pm 1)] \langle f_l^m | f_l^m \rangle = \hbar^2 [l(l+1) - m(m \pm 1)] \\ &= \langle L_{\pm} f_l^m | L_{\pm} f_l^m \rangle = \langle A_l^m f_l^{m \pm 1} | A_l^m f_l^{m \pm 1} \rangle = |A_l^m|^2 \langle f_l^{m \pm 1} | f_l^{m \pm 1} \rangle = |A_l^m|^2. \end{aligned}$$

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Conclusion: $A_l^m = \hbar\sqrt{l(l+1) - m(m \pm 1)}$

Problem 4.19

(a)

$$[L_z, x] = [xp_y - yp_x, x] = [xp_y, x] - [yp_x, x] = 0 - y[p_x, x] = i\hbar y. \checkmark$$

$$[L_z, y] = [xp_y - yp_x, y] = [xp_y, y] - [yp_x, y] = x[p_y, y] - 0 = -i\hbar x. \checkmark$$

$$[L_z, z] = [xp_y - yp_x, z] = [xp_y, z] - [yp_x, z] = 0 - 0 = 0. \checkmark$$

$$[L_z, p_x] = [xp_y - yp_x, p_x] = [xp_y, p_x] - [yp_x, p_x] = p_y[x, p_x] - 0 = i\hbar p_y. \checkmark$$

$$[L_z, p_y] = [xp_y - yp_x, p_y] = [xp_y, p_y] - [yp_x, p_y] = 0 - p_x[y, p_y] = -i\hbar p_x. \checkmark$$

$$[L_z, p_z] = [xp_y - yp_x, p_z] = [xp_y, p_z] - [yp_x, p_z] = 0 - 0 = 0. \checkmark$$

(b)

$$\begin{aligned} [L_z, L_x] &= [L_z, yp_z - zp_y] = [L_z, yp_z] - [L_z, zp_y] = [L_z, y]p_z - [L_z, p_y]z \\ &= -i\hbar xp_z + i\hbar p_x z = i\hbar(zp_x - xp_z) = i\hbar L_y. \end{aligned}$$

(So, by cyclic permutation of the indices, $[L_x, L_y] = i\hbar L_z$.)

(c)

$$\begin{aligned} [L_z, r^2] &= [L_z, x^2] + [L_z, y^2] + [L_z, z^2] = [L_z, x]x + x[L_z, x] + [L_z, y]y + y[L_z, y] + 0 \\ &= i\hbar yx + x i\hbar y + (-i\hbar x)y + y(-i\hbar x) = \boxed{0}. \end{aligned}$$

$$\begin{aligned} [L_z, p^2] &= [L_z, p_x^2] + [L_z, p_y^2] + [L_z, p_z^2] = [L_z, p_x]p_x + p_x[L_z, p_x] + [L_z, p_y]p_y + p_y[L_z, p_y] + 0 \\ &= i\hbar p_y p_x + p_x i\hbar p_y + (-i\hbar p_x)p_y + p_y(-i\hbar p_x) = \boxed{0}. \end{aligned}$$

(d) It follows from (c) that all three components of \mathbf{L} commute with r^2 and p^2 , and hence with the whole Hamiltonian, since $H = p^2/2m + V(\sqrt{r^2})$. QED

Problem 4.21

(a)

$$\begin{aligned}
 L_+ L_- f &= -\hbar^2 e^{i\phi} \left(\frac{\partial}{\partial \theta} + i \cot \theta \frac{\partial}{\partial \phi} \right) \left[e^{-i\phi} \left(\frac{\partial f}{\partial \theta} - i \cot \theta \frac{\partial f}{\partial \phi} \right) \right] \\
 &= -\hbar^2 e^{i\phi} \left\{ e^{-i\phi} \left[\frac{\partial^2 f}{\partial \theta^2} - i \left(-\csc^2 \theta \frac{\partial f}{\partial \phi} + \cot \theta \frac{\partial^2 f}{\partial \theta \partial \phi} \right) \right] \right. \\
 &\quad \left. + i \cot \theta \left[-i e^{-i\phi} \left(\frac{\partial f}{\partial \theta} - i \cot \theta \frac{\partial f}{\partial \phi} \right) + e^{-i\phi} \left(\frac{\partial^2 f}{\partial \phi \partial \theta} - i \cot \theta \frac{\partial^2 f}{\partial \phi^2} \right) \right] \right\} \\
 &= -\hbar^2 \left(\frac{\partial^2 f}{\partial \theta^2} + i \csc^2 \theta \frac{\partial f}{\partial \phi} - i \cot \theta \frac{\partial^2 f}{\partial \theta \partial \phi} + \cot \theta \frac{\partial f}{\partial \theta} - i \cot^2 \theta \frac{\partial f}{\partial \phi} + i \cot \theta \frac{\partial^2 f}{\partial \phi \partial \theta} + \cot^2 \theta \frac{\partial^2 f}{\partial \phi^2} \right) \\
 &= -\hbar^2 \left[\frac{\partial^2}{\partial \theta^2} + \cot \theta \frac{\partial}{\partial \theta} + \cot^2 \theta \frac{\partial^2}{\partial \phi^2} + i(\csc^2 \theta - \cot^2 \theta) \frac{\partial}{\partial \phi} \right] f, \text{ so} \\
 L_+ L_- &= -\hbar^2 \left(\frac{\partial^2}{\partial \theta^2} + \cot \theta \frac{\partial}{\partial \theta} + \cot^2 \theta \frac{\partial^2}{\partial \phi^2} + i \frac{\partial}{\partial \phi} \right). \text{ QED}
 \end{aligned}$$

(b) Equation 4.129 $\Rightarrow L_z = \frac{\hbar}{i} \frac{\partial}{\partial \phi}$, Eq. 4.112 $\Rightarrow L^2 = L_+ L_- + L_- L_+ + \hbar L_z$, so, using (a):

$$\begin{aligned}
 L^2 &= -\hbar^2 \left(\frac{\partial^2}{\partial \theta^2} + \cot \theta \frac{\partial}{\partial \theta} + \cot^2 \theta \frac{\partial^2}{\partial \phi^2} + i \frac{\partial}{\partial \phi} \right) - \hbar^2 \frac{\partial^2}{\partial \phi^2} - \hbar \left(\frac{\hbar}{i} \right) \frac{\partial}{\partial \phi} \\
 &= -\hbar^2 \left(\frac{\partial^2}{\partial \theta^2} + \cot \theta \frac{\partial}{\partial \theta} + (\cot^2 \theta + 1) \frac{\partial^2}{\partial \phi^2} + i \frac{\partial}{\partial \phi} - i \frac{\partial}{\partial \phi} \right) = -\hbar^2 \left(\frac{\partial^2}{\partial \theta^2} + \cot \theta \frac{\partial}{\partial \theta} + \frac{1}{\sin^2 \theta} \frac{\partial^2}{\partial \phi^2} \right) \\
 &= -\hbar^2 \left[\frac{1}{\sin \theta} \frac{\partial}{\partial \theta} \left(\sin \theta \frac{\partial}{\partial \theta} \right) + \frac{1}{\sin^2 \theta} \frac{\partial^2}{\partial \phi^2} \right]. \text{ QED}
 \end{aligned}$$

Problem 4.22

(a) $L_+ Y_l^l = 0$ (top of the ladder).

(b)

$$L_+ Y_l^l = l \hbar Y_l^l \Rightarrow \frac{\hbar}{i} \frac{\partial}{\partial \phi} Y_l^l = l \hbar Y_l^l, \quad \text{so } \frac{\partial Y_l^l}{\partial \phi} = i Y_l^l, \quad \text{and hence } Y_l^l = f(\theta) e^{il\phi}.$$

[Note: $f(\theta)$ is the "constant" here – it's constant with respect to ϕ ... but still can depend on θ .]

$$L_+ Y_l^l = 0 \Rightarrow \hbar e^{i\phi} \left(\frac{\partial}{\partial \theta} + i \cot \theta \frac{\partial}{\partial \phi} \right) [f(\theta) e^{il\phi}] = 0, \quad \text{or } \frac{df}{d\theta} e^{il\phi} + i f \cot \theta i l e^{il\phi} = 0, \quad \text{so}$$

$$\frac{df}{d\theta} = l \cot \theta f \Rightarrow \frac{df}{f} = l \cot \theta d\theta \Rightarrow \int \frac{df}{f} = l \int \frac{\cos \theta}{\sin \theta} d\theta \Rightarrow \ln f = l \ln(\sin \theta) + \text{constant}.$$

$$\ln f = \ln(\sin^l \theta) + K \Rightarrow \ln \left(\frac{f}{\sin^l \theta} \right) = K \Rightarrow \frac{f}{\sin^l \theta} = \text{constant} \Rightarrow f(\theta) = A \sin^l \theta.$$

$$Y_l^l(\theta, \phi) = A (e^{i\phi} \sin \theta)^l.$$

(c)

$$1 = A^2 \int \sin^{2l} \theta \sin \theta d\theta d\phi = 2\pi A^2 \int_0^\pi \sin^{(2l+1)} \theta d\theta = 2\pi A^2 2 \frac{(2 \cdot 4 \cdot 6 \cdots (2l))}{1 \cdot 3 \cdot 5 \cdots (2l+1)}$$

$$= 4\pi A^2 \frac{(2 \cdot 4 \cdot 6 \cdots 2l)^2}{1 \cdot 2 \cdot 3 \cdot 4 \cdot 5 \cdots (2l+1)} = 4\pi A^2 \frac{(2^l l!)^2}{(2l+1)!}, \quad \text{so } A = \frac{1}{2^{l+1} l!} \sqrt{\frac{(2l+1)!}{\pi}},$$

the same as Problem 4.5, except for an overall factor of $(-1)^l$, which is arbitrary anyway.

Problem 4.27

(a)

$$\chi^\dagger \chi = |A|^2(9 + 16) = 25|A|^2 = 1 \Rightarrow \boxed{A = 1/5.}$$

(b)

$$\langle S_x \rangle = \chi^\dagger S_x \chi = \frac{1}{25} \frac{\hbar}{2} (-3i \ 4) \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix} \begin{pmatrix} 3i \\ 4 \end{pmatrix} = \frac{\hbar}{50} (-3i \ 4) \begin{pmatrix} 4 \\ 3i \end{pmatrix} = \frac{\hbar}{50} (12i + 12i) = \boxed{0.}$$

$$\langle S_y \rangle = \chi^\dagger S_y \chi = \frac{1}{25} \frac{\hbar}{2} (-3i \ 4) \begin{pmatrix} 0 & -i \\ i & 0 \end{pmatrix} \begin{pmatrix} 3i \\ 4 \end{pmatrix} = \frac{\hbar}{50} (-3i \ 4) \begin{pmatrix} -4i \\ -3 \end{pmatrix} = \frac{\hbar}{50} (-12 - 12i) = \boxed{-\frac{12}{25}\hbar.}$$

$$\langle S_z \rangle = \chi^\dagger S_z \chi = \frac{1}{25} \frac{\hbar}{2} (-3i \ 4) \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix} \begin{pmatrix} 3i \\ 4 \end{pmatrix} = \frac{\hbar}{50} (-3i \ 4) \begin{pmatrix} 3i \\ -4 \end{pmatrix} = \frac{\hbar}{50} (9 - 16) = \boxed{-\frac{7}{50}\hbar.}$$

(c)

$$\langle S_x^2 \rangle = \langle S_y^2 \rangle = \langle S_z^2 \rangle = \frac{\hbar^2}{4} \text{ (always, for spin } 1/2\text{), so } \sigma_{S_x}^2 = \langle S_x^2 \rangle - \langle S_x \rangle^2 = \frac{\hbar^2}{4} = 0, \quad \boxed{\sigma_{S_x} = \frac{\hbar}{2}.}$$

$$\sigma_{S_y}^2 = \langle S_y^2 \rangle - \langle S_y \rangle^2 = \frac{\hbar^2}{4} - \left(\frac{12}{25}\right)^2 \hbar^2 = \frac{\hbar^2}{2500} (625 - 576) = \frac{49}{2500} \hbar^2, \quad \boxed{\sigma_{S_y} = \frac{7}{50}\hbar.}$$

$$\sigma_{S_z}^2 = \langle S_z^2 \rangle - \langle S_z \rangle^2 = \frac{\hbar^2}{4} - \left(\frac{7}{50}\right)^2 \hbar^2 = \frac{\hbar^2}{2500} (625 - 49) = \frac{576}{2500} \hbar^2, \quad \boxed{\sigma_{S_z} = \frac{12}{25}\hbar.}$$

(d)

$$\sigma_{S_x} \sigma_{S_x} = \frac{\hbar}{2} \cdot \frac{7}{50} \hbar \geq \frac{7}{2} \frac{\hbar}{50} |\langle S_x \rangle| = \frac{\hbar}{2} \cdot \frac{7}{50} \hbar \quad \text{(right at the uncertainty limit). } \checkmark$$

$$\sigma_{S_x} \sigma_{S_x} = \frac{7}{50} \hbar \cdot \frac{12}{25} \hbar \geq \frac{7}{2} \frac{\hbar}{25} |\langle S_x \rangle| = 0 \quad \text{(trivial). } \checkmark$$

$$\sigma_{S_x} \sigma_{S_x} = \frac{12}{25} \hbar \cdot \frac{\hbar}{2} \geq \frac{\hbar}{2} \frac{12}{25} |\langle S_y \rangle| = \frac{\hbar}{2} \cdot \frac{12}{25} \hbar \quad \text{(right at the uncertainty limit). } \checkmark$$

Problem 4.28

$$\langle S_x \rangle = \frac{\hbar}{2} (a^* \ b^*) \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix} \begin{pmatrix} a \\ b \end{pmatrix} = \frac{\hbar}{2} (a^* \ b^*) \begin{pmatrix} b \\ a \end{pmatrix} = \boxed{\frac{\hbar}{2}(a^*b + b^*a)} = \hbar \operatorname{Re}(ab^*).$$

$$\begin{aligned} \langle S_y \rangle &= \frac{\hbar}{2} (a^* \ b^*) \begin{pmatrix} 0 & -i \\ i & 0 \end{pmatrix} \begin{pmatrix} a \\ b \end{pmatrix} = \frac{\hbar}{2} (a^* \ b^*) \begin{pmatrix} -ib \\ ia \end{pmatrix} \\ &= \frac{\hbar}{2} (-ia^*b + iab^*) = \boxed{\frac{\hbar}{2}i(ab^* - a^*b)} = -\hbar \operatorname{Im}(ab^*). \end{aligned}$$

$$\langle S_z \rangle = \frac{\hbar}{2} (a^* \ b^*) \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix} \begin{pmatrix} a \\ b \end{pmatrix} = \frac{\hbar}{2} (a^* \ b^*) \begin{pmatrix} a \\ -b \end{pmatrix} = \frac{\hbar}{2} (a^*a - b^*b) = \boxed{\frac{\hbar}{2}(|a|^2 - |b|^2)}.$$

$$S_x^2 = \frac{\hbar^2}{4} \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix} \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix} = \frac{\hbar^2}{4} \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix} = \frac{\hbar^2}{4} I; \quad S_y^2 = \frac{\hbar^2}{4} \begin{pmatrix} 0 & -i \\ i & 0 \end{pmatrix} \begin{pmatrix} 0 & -i \\ i & 0 \end{pmatrix} = \frac{\hbar^2}{4} I;$$

$$S_z^2 = \frac{\hbar^2}{4} \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix} \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix} = \frac{\hbar^2}{4} I; \quad \text{so } \boxed{\langle S_x^2 \rangle = \langle S_y^2 \rangle = \langle S_z^2 \rangle = \frac{\hbar^2}{4}}.$$

$$\langle S_x^2 \rangle + \langle S_y^2 \rangle + \langle S_z^2 \rangle = \frac{3}{4} \hbar^2 \stackrel{?}{=} s(s+1)\hbar^2 = \frac{1}{2}(\frac{1}{2}+1)\hbar^2 = \frac{3}{4} \hbar^2 = \langle S^2 \rangle. \checkmark$$

Problem 4.29

(a)

$$S_y = \frac{\hbar}{2} \begin{pmatrix} 0 & -i \\ i & 0 \end{pmatrix}; \quad \begin{vmatrix} -\lambda & -ih/2 \\ ih/2 & -\lambda \end{vmatrix} = \lambda^2 - \frac{\hbar^2}{4} \Rightarrow \boxed{\lambda = \pm \frac{\hbar}{2}} \text{ (of course).}$$

$$\frac{\hbar}{2} \begin{pmatrix} 0 & -i \\ i & 0 \end{pmatrix} \begin{pmatrix} \alpha \\ \beta \end{pmatrix} = \pm \frac{\hbar}{2} \begin{pmatrix} \alpha \\ \beta \end{pmatrix} \Rightarrow -i\beta = \pm \alpha; \quad |\alpha|^2 + |\beta|^2 = 1 \Rightarrow |\alpha|^2 + |\alpha|^2 = 1 \Rightarrow \alpha = \frac{1}{\sqrt{2}}.$$

$$\boxed{\chi_+^{(y)} = \frac{1}{\sqrt{2}} \begin{pmatrix} 1 \\ i \end{pmatrix}; \quad \chi_-^{(y)} = \frac{1}{\sqrt{2}} \begin{pmatrix} 1 \\ -i \end{pmatrix}}.$$

(b)

$$c_+ = \left(\chi_+^{(y)} \right)^\dagger \chi = \frac{1}{\sqrt{2}} (1 \ -i) \begin{pmatrix} a \\ b \end{pmatrix} = \frac{1}{\sqrt{2}} (a - ib); \quad \boxed{+\frac{\hbar}{2}, \text{ with probability } \frac{1}{2}|a - ib|^2}.$$

$$c_- = \left(\chi_-^{(y)} \right)^\dagger \chi = \frac{1}{\sqrt{2}} (1 \ i) \begin{pmatrix} a \\ b \end{pmatrix} = \frac{1}{\sqrt{2}} (a + ib); \quad \boxed{-\frac{\hbar}{2}, \text{ with probability } \frac{1}{2}|a + ib|^2}.$$

$$\begin{aligned} P_+ + P_- &= \frac{1}{2} [(a^* + ib^*)(a - ib) + (a^* - ib^*)(a + ib)] \\ &= \frac{1}{2} [|a|^2 - ia^*b + iab^* + |b|^2 + |a|^2 + ia^*b - iab^* + |b|^2] = |a|^2 + |b|^2 = 1. \checkmark \end{aligned}$$

$$(c) \quad \boxed{\frac{\hbar^2}{4}, \text{ with probability } 1}.$$

Problem 4.30