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| Question: | 1 | 2 | 3 | 4 | Total |
| :--- | :---: | :---: | :---: | :---: | :---: |
| Points: | 8 | 10 | 22 | 10 | 50 |
| Score: |  |  |  |  |  |




Figure 1: The sequence $x[n]$ consists of $N=201$ samples, where the sampling interval is $T=1 \mathrm{~ms}$ and the time of first sample is zero.

(a) [2 points] What is the Nyquist frequency, in Hz (cycles per second)?
(b) [2 points] Label the time axis, with units of seconds.
(c) [2 points] In the amplitude spectrum, the minimum frequency plotted is zero. The maximum frequency plotted is not the Nyquist frequency. Label the frequency axis, with units of Hz .
(d) [2 points] The sequence $x[n]$ is contaminated with high-frequency noise with relatively low amplitude. At what frequency (in Hz ) is this noise apparent in the amplitude spectrum?
 For the sequence $x[n]$ in Figure 1, consider the task of attenuating the highfrequency noise with a frequency-domain filter. The sequence $x[n]$ contains 201 samples, and you choose an FFT length $N=400$ samples.
(a) [2 points] $201=3 \times 67$. Explain why you would not choose an FFT length $N=201$.
(b) [2 points] $216=2 \times 2 \times 2 \times 3 \times 3 \times 3$. Explain why an FFT length $N=216$ might be too small.
(c) [2 points] After the FFT, the values $X[k]$ are generally complex, with real and imaginary parts. For which two indices $k$ are the imaginary parts guaranteed to be zero?
(d) [2 points] What is the frequency sampling interval $\Delta F$, in Hz ?
(e) [2 points] Determine the index $k_{0}$ of the sample in $X[k]$ that contains most of the noise.

Refer to the sequence $x[n]$ and amplitude spectrum in Figure 1. Design a causal notch filter to zero anything at the noise frequency, while preserving signal at other frequencies.
(a) [4 points] Sketch the locations of the poles and zeros for your filter.
(b) [4 points] Sketch the amplitude and phase responses $A(\omega)$ and $\phi(\omega)$ of your system for $-\pi<\omega<\pi$. (Units of $\omega$ are radians per sample.)
(c) [4 points] Specify the system response $H(z)$ of your filter. Include a scale factor to ensure that the zero-frequency (DC) response is one. Define all coefficients $\left(b_{0}, b_{1}, \ldots\right)$ in $H(z)$, but assume that a computer program will be used to compute their numerical values.
(d) [2 points] Write a linear constant-coefficient difference equation for the output $y[n]$ of your system in terms of the input $x[n]$.
(e) [2 points] Now suppose that you apply your notch filter in the opposite direction so that the system is anti-causal. Again express the output $y[n]$ in terms of the input $x[n]$.
(f) [2 points] Specify the system response $H(z)$ of the anti-causal filter.
(g) [2 points] Sketch the amplitude and phase responses $A(\omega)$ and $\phi(\omega)$ of the anti-causal filter, for $-\pi<\omega<\pi$.
(h) [2 points] Let $y_{1}[n]$ denote the output of the causal system and $y_{2}[n]$ the output of the anti-causal system. We can apply both filters and average the two outputs to obtain the composite output $y[n]=\left(y_{1}[n]+y_{2}[n]\right) / 2$. Sketch the amplitude and phase responses $A(\omega)$ and $\phi(\omega)$ of the composite system, for $-\pi<\omega<\pi$.
 Consider resampling the sequence $x[n]$ of Figure 1, without anti-alias filtering.
(a) [4 points] Specify a resampling system for output $y_{1}[n]$ with sampling interval 2 ms . Express the output $y_{1}[n]$ in terms of the input $x[n]$.
(b) [2 points] At what frequency less than 250 Hz will aliased high-frequency noise be apparent in the output $y_{1}[n]$.
(c) [4 points] Specify a resampling system for output $y_{2}[n]$ with sampling interval 0.1 ms . Express the output $y_{2}[n]$ in terms of the input $x[n]$.

