## GPGN 404 1st Midterm Exam September 28, 2012

Name: \_\_\_\_\_

Question:	1	2	3	4	5	Total
Points:	6	6	14	12	12	50
Score:						

- (a) Specify two different non-negative frequencies f for which the sequence  $x[n] = \cos(2\pi f n)$  is periodic with period N = 8 samples.
- (b) Specify a frequency f for which the same sequence x[n] is not periodic.

(a) Sketch the impulse response of this system.

(b) Rewrite this system as a convolution sum, by completing the equation below with only input samples x on the right-hand-side.

y[n] =

$$h_1[n] = \delta[n] - \delta[n-1]$$
$$h_2[n] = \delta[n+1] - \delta[n]$$

- (a) Sketch the two impulse responses  $h_1[n]$  and  $h_2[n]$ .
- (b) For an input unit-step sequence x[n] = u[n], sketch outputs  $y_1[n]$  and  $y_2[n]$  for these two systems.

(c) For the same input x[n] = u[n], sketch both the impulse response h[n]and output y[n] of the composite system with impulse response  $h[n] = h_1[n] * h_2[n]$ , where \* denotes convolution.

(d) For the same input x[n] = u[n], sketch both the impulse response h[n]and output y[n] of the composite system with impulse response  $h[n] = \frac{1}{2}(h_1[n] + h_2[n])$ . (a) Sketch the impulse responses of these two systems.

(b) Both systems are stable. For each system, express the bound  $B_y$  on the output in terms of the bound  $B_x$  on the input.

(c) Write two computer program *fragments* that show how you would compute output sequences y1[n] and y2[n] for any input sequence x[n], for all n = 0, 1, ..., nt-1. Omit statements that construct arrays, get nt, etc.

$$h[n] = \delta[n-1] + \delta[n] + \delta[n+1].$$

- (a) Sketch the impulse response h[n] for this system.
- (b) Express the output y[n] of this system in terms of the input x[n].
- (c) For input x[n] = u[n] (the unit-step sequence), sketch the output y[n].
- (d) What is the real-valued (no complex numbers) frequency response  $H(\omega)$  of this system?
- (e) What frequencies  $\omega$  in the interval  $[-\pi, \pi]$  are zeroed by this system?
- (f) How could you modify this system so that the DC (zero-frequency) response H(0) = 1, while preserving the shape of its impulse response h[n]?